

# A hierarchical approach to joint estimation of juvenile salmonid abundance and detection efficiency

*Rethinking methods for quantifying snorkel survey detection efficiency*

March 5, 2020  
Oregon Chapter AFS Meeting

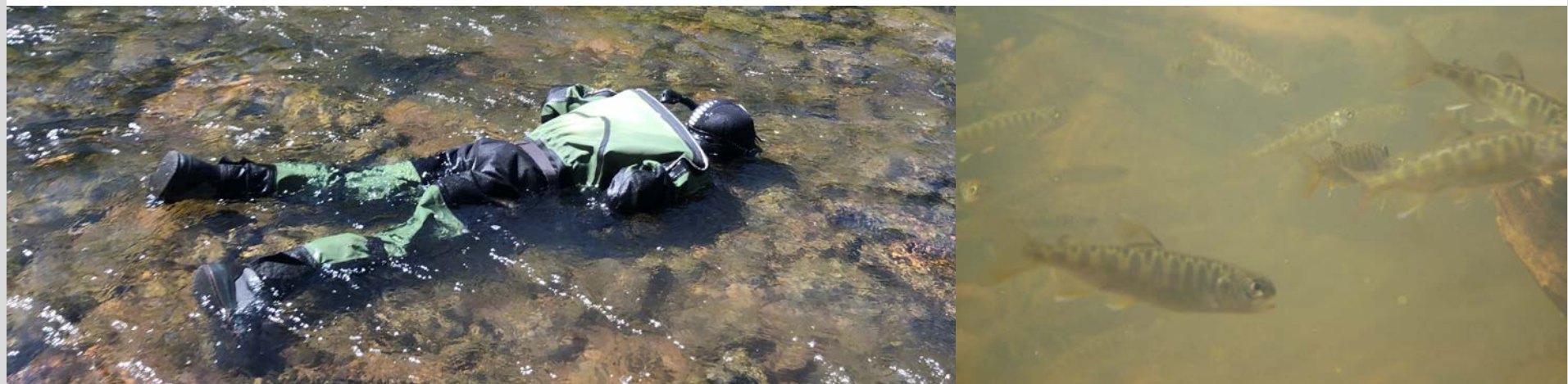


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<sup>3</sup>Department of Fish and Wildlife, Oregon State University



# Snorkel Surveys

*What are they?*

- Basically what they sound like
- Intended to count juvenile salmonids
- Summer base-flow counts
- Data: counts of fish
  - By species, size class





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- Fish vs. \_\_\_\_\_ relationships
  - Habitat type/quality/restoration
  - Den. dep. growth/mortality
  - Weighted usable habitat metrics
- Substantial observation errors



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# Snorkel Surveys

*Types of observation errors*

(1) Partial Detectability (*individual fish may not be seen*)

(2) Misclassification

- Double, triple, etc. counting
- Incorrect species assignment
- Incorrect size class assignment

(3) Transcription (*counts may be incorrectly recorded*)



# Snorkel Surveys

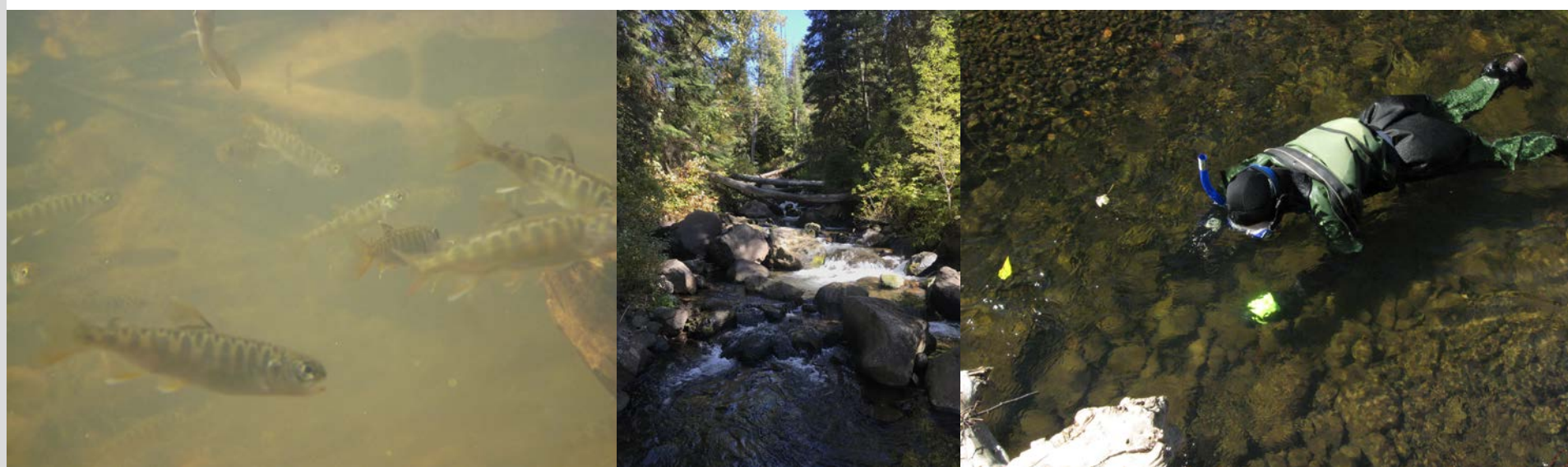
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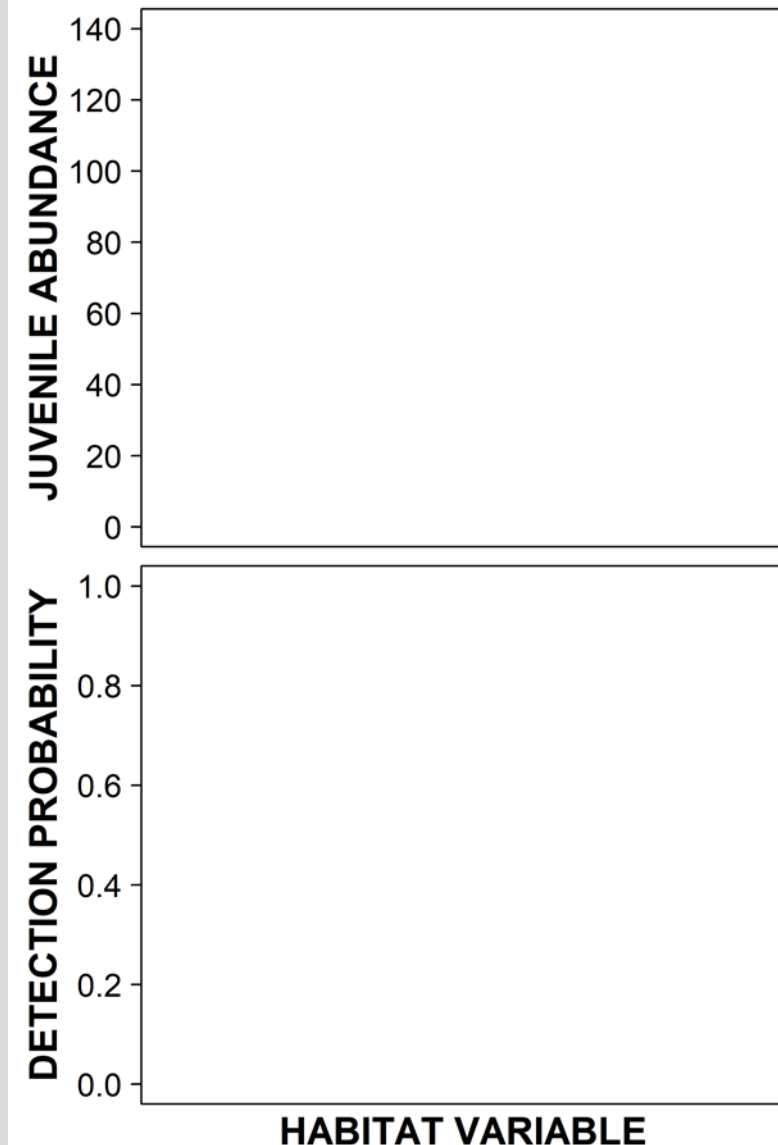
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# Partial Detectability in Snorkel Surveys

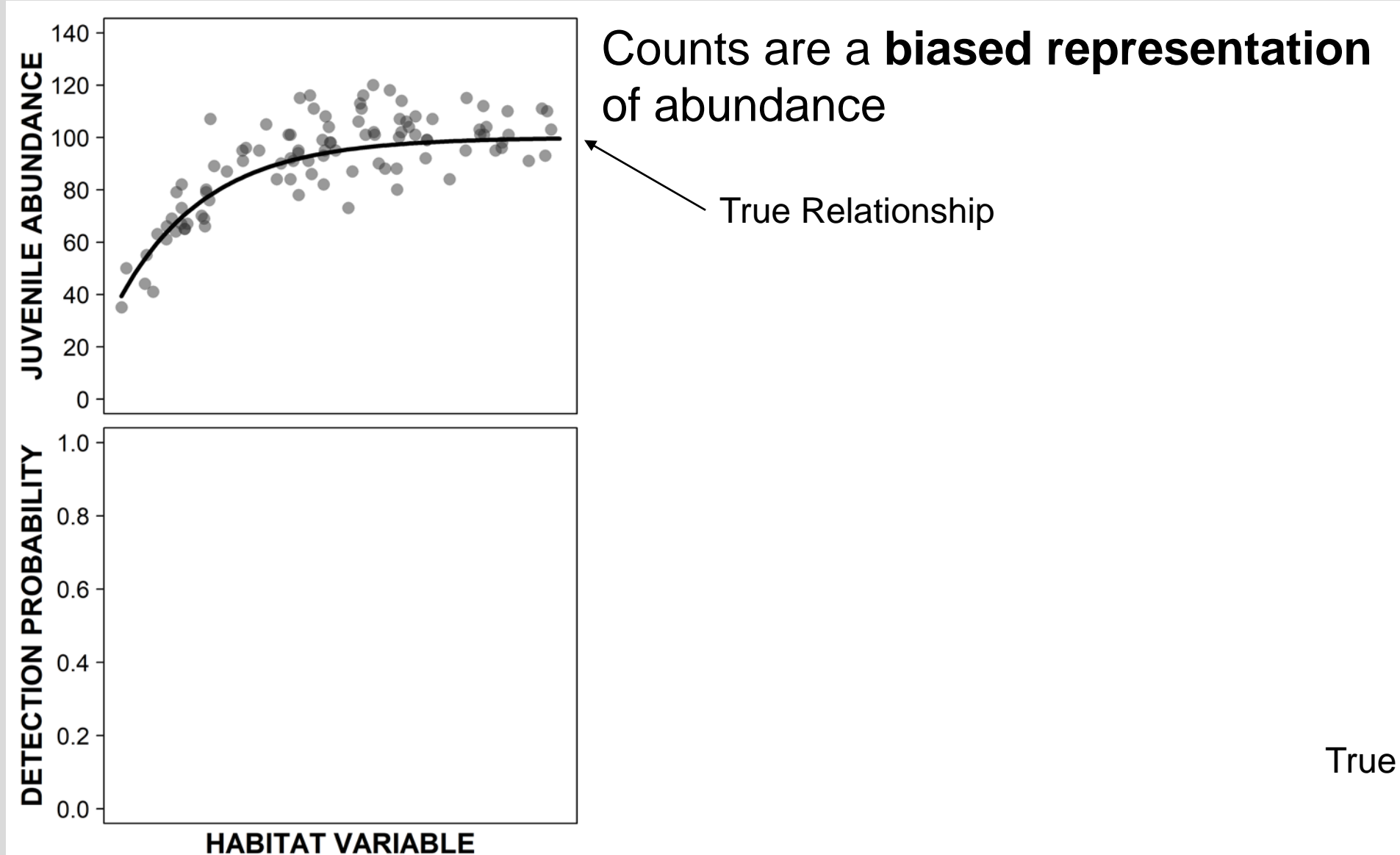
*Why does it matter?*



Counts are a **biased representation** of abundance

# Partial Detectability in Snorkel Surveys

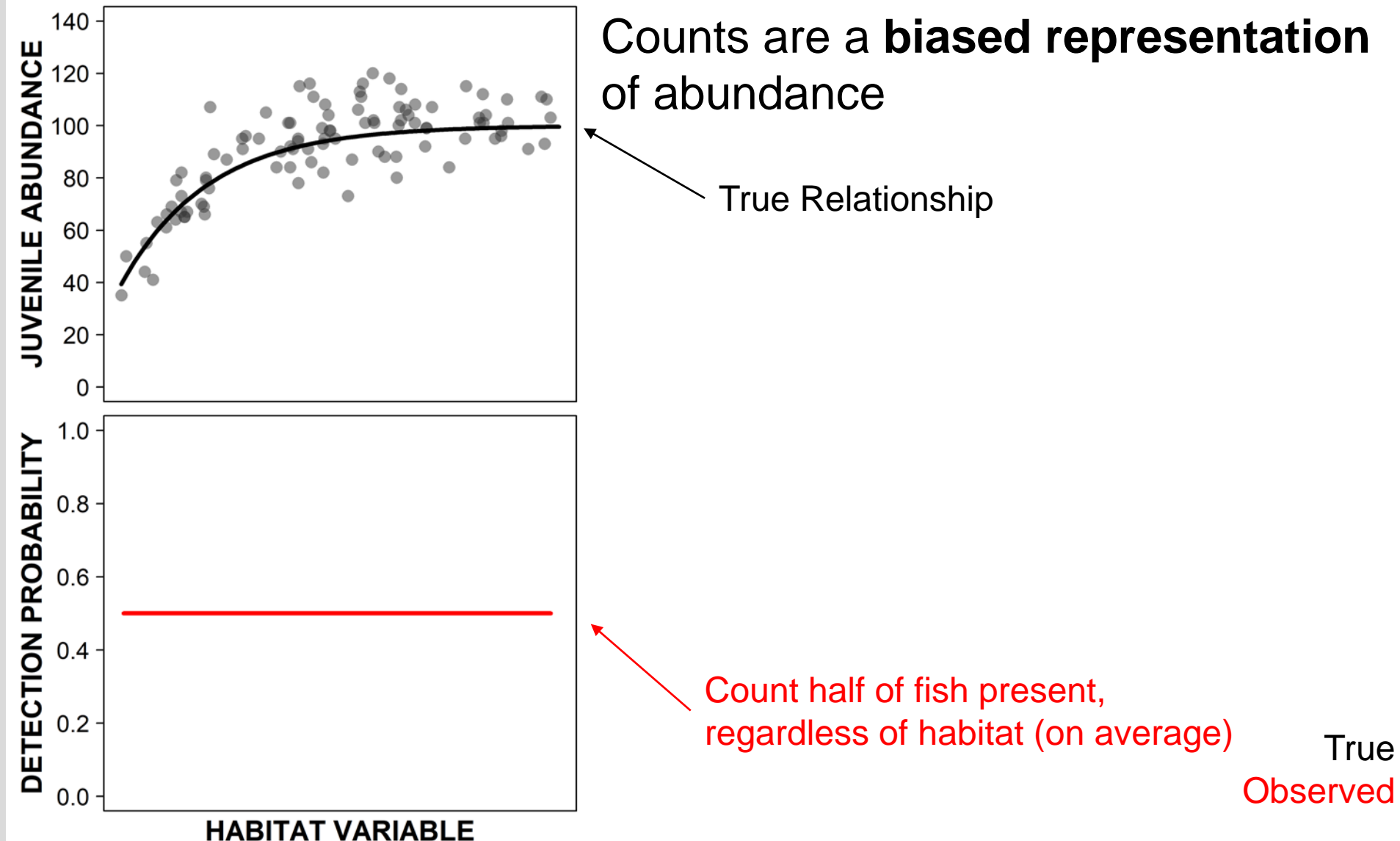
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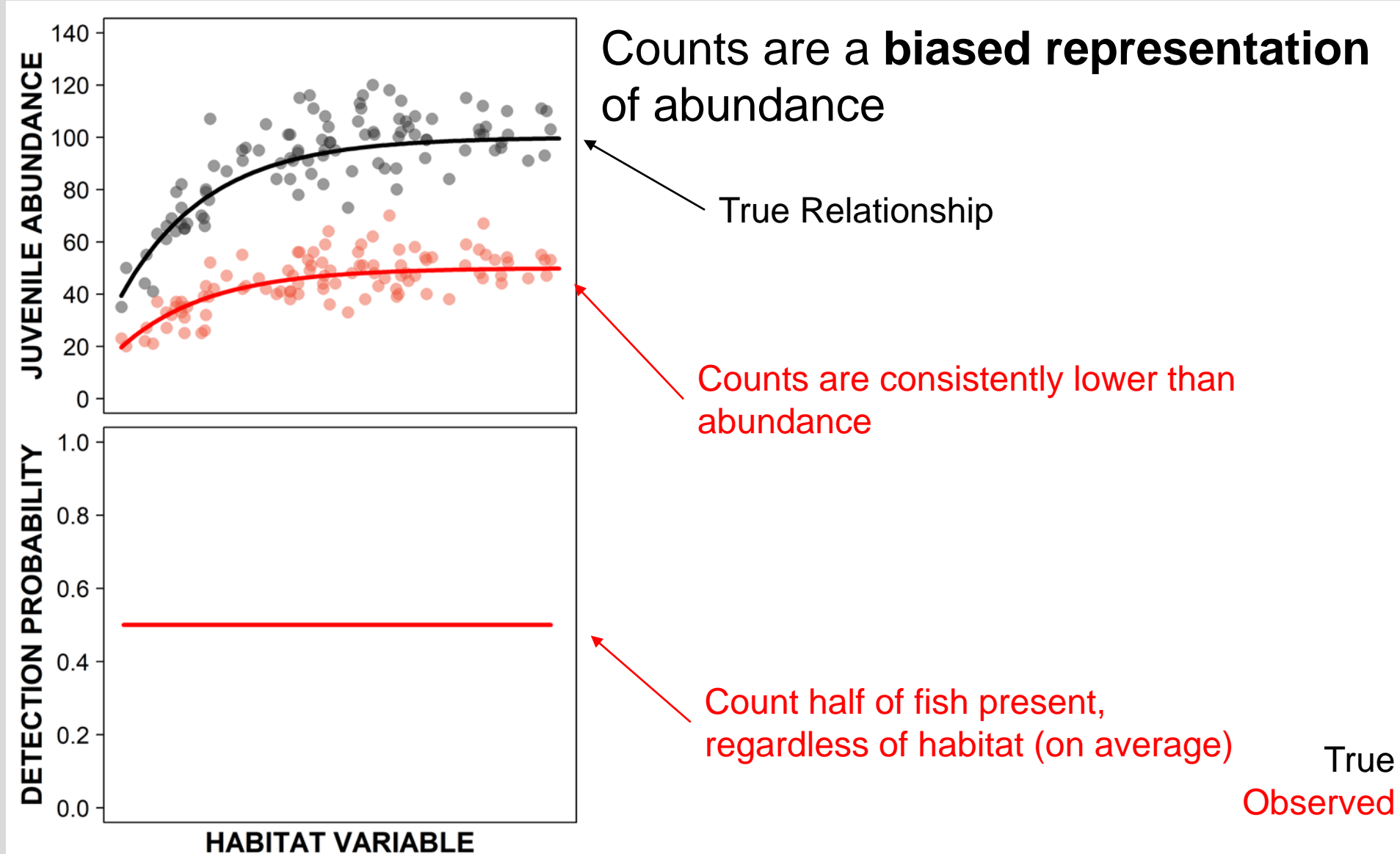
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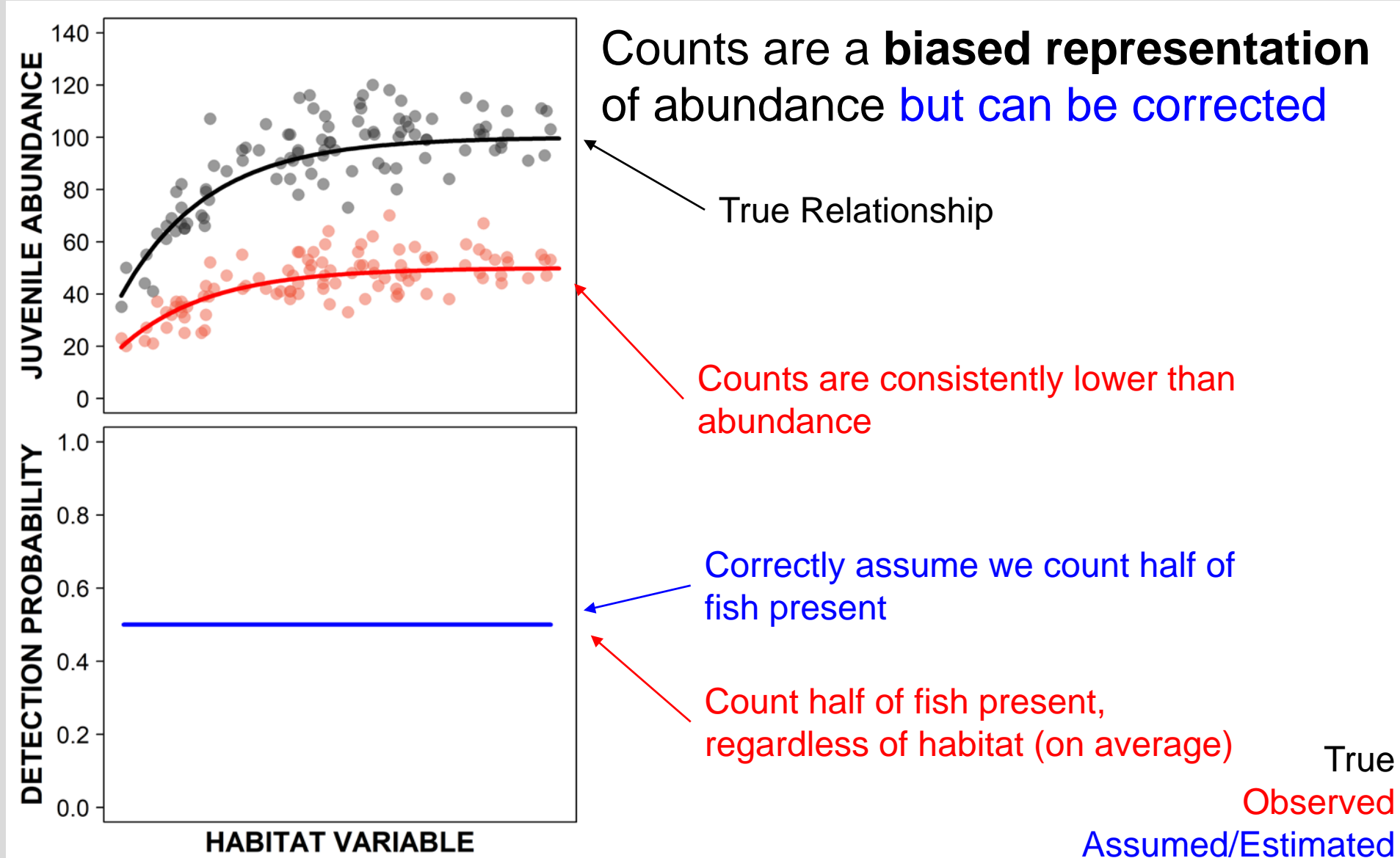
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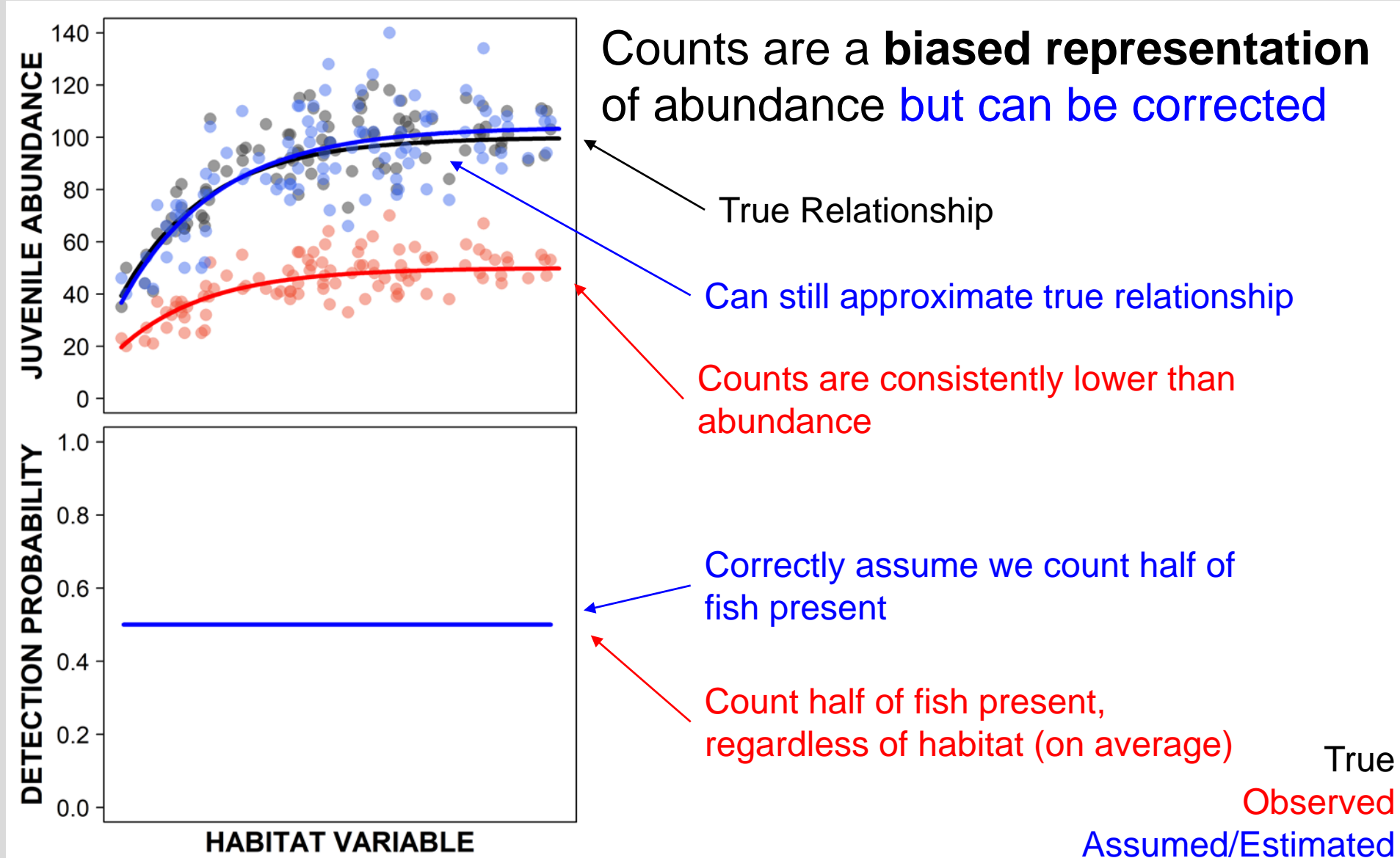
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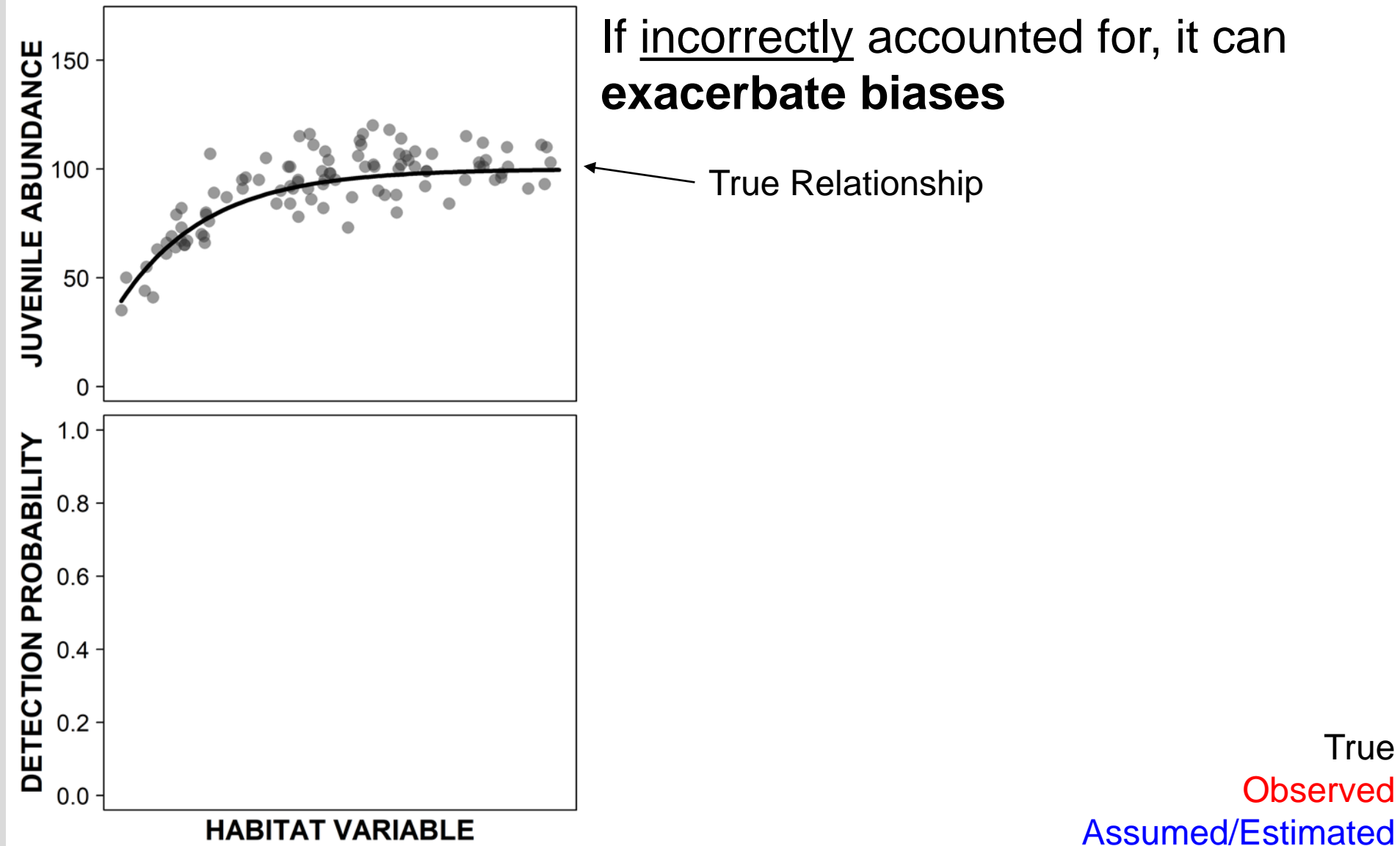
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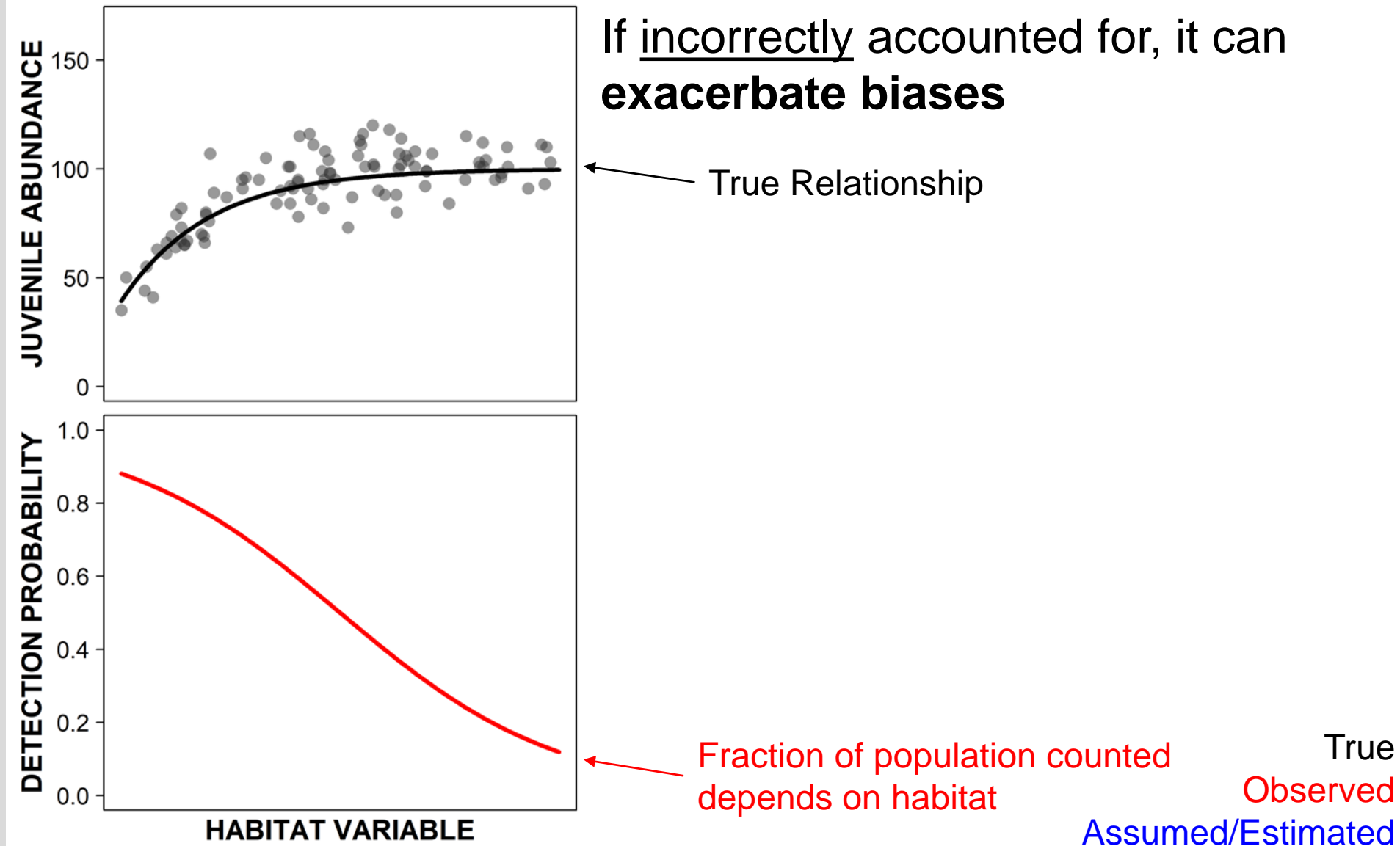
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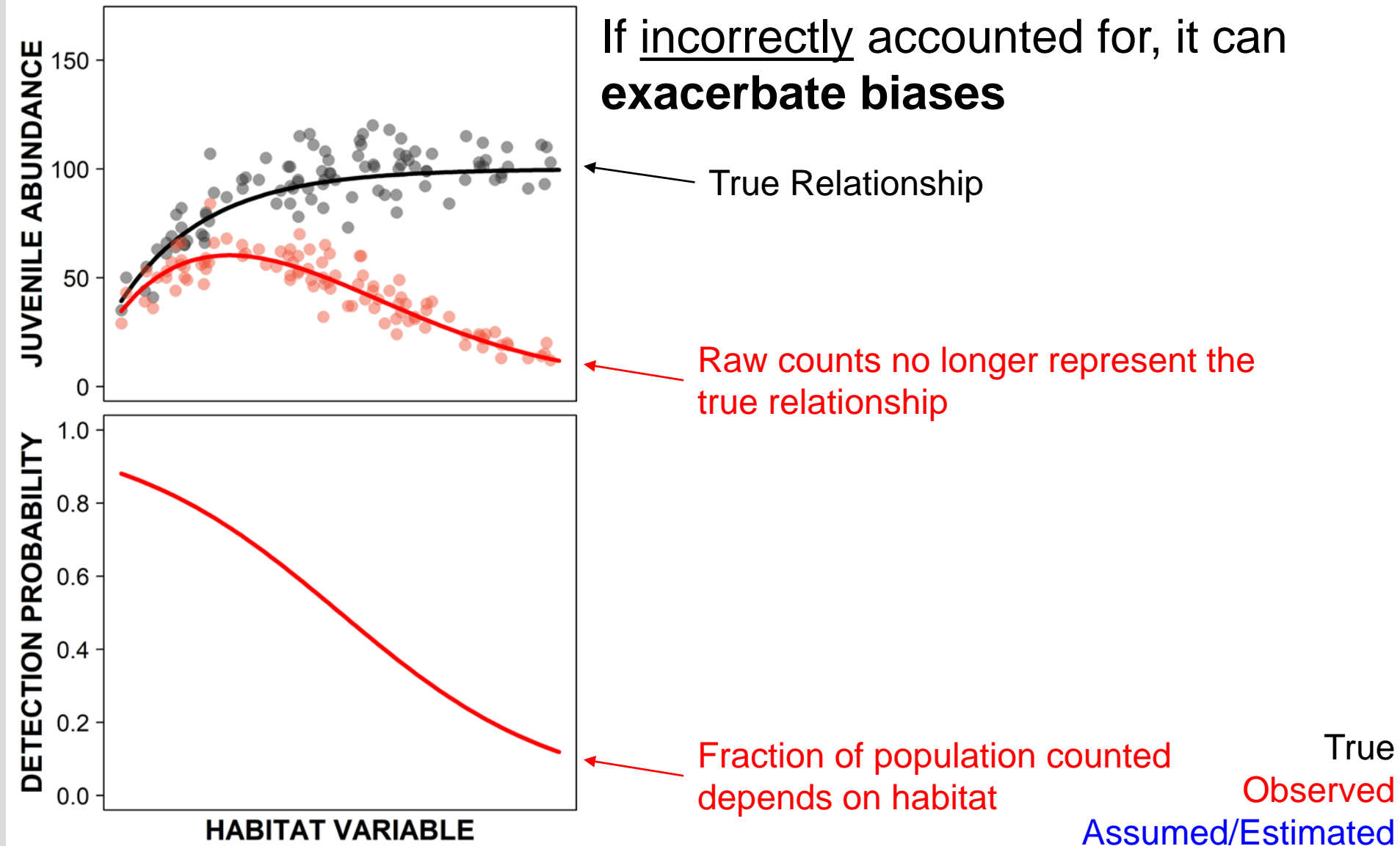
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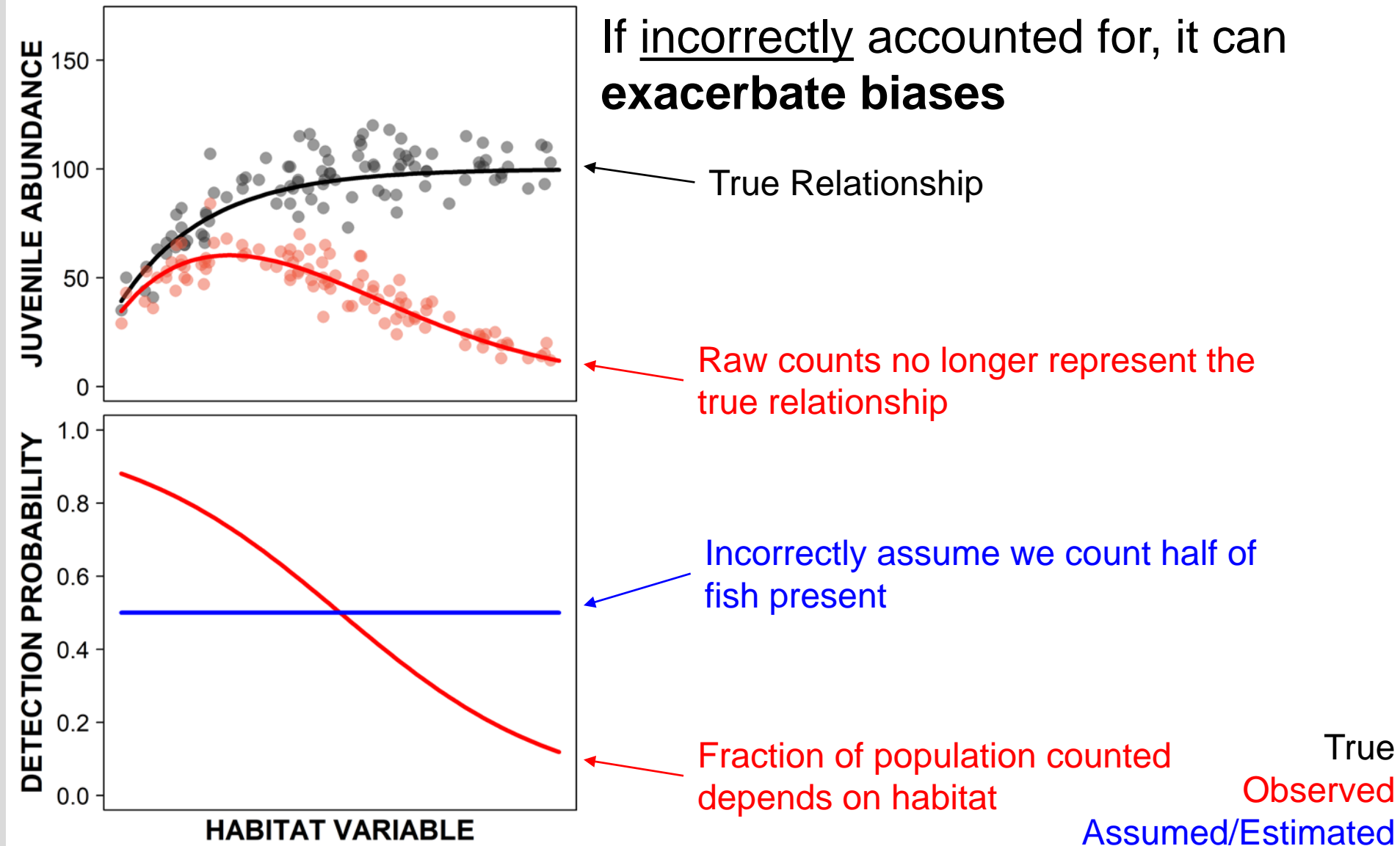
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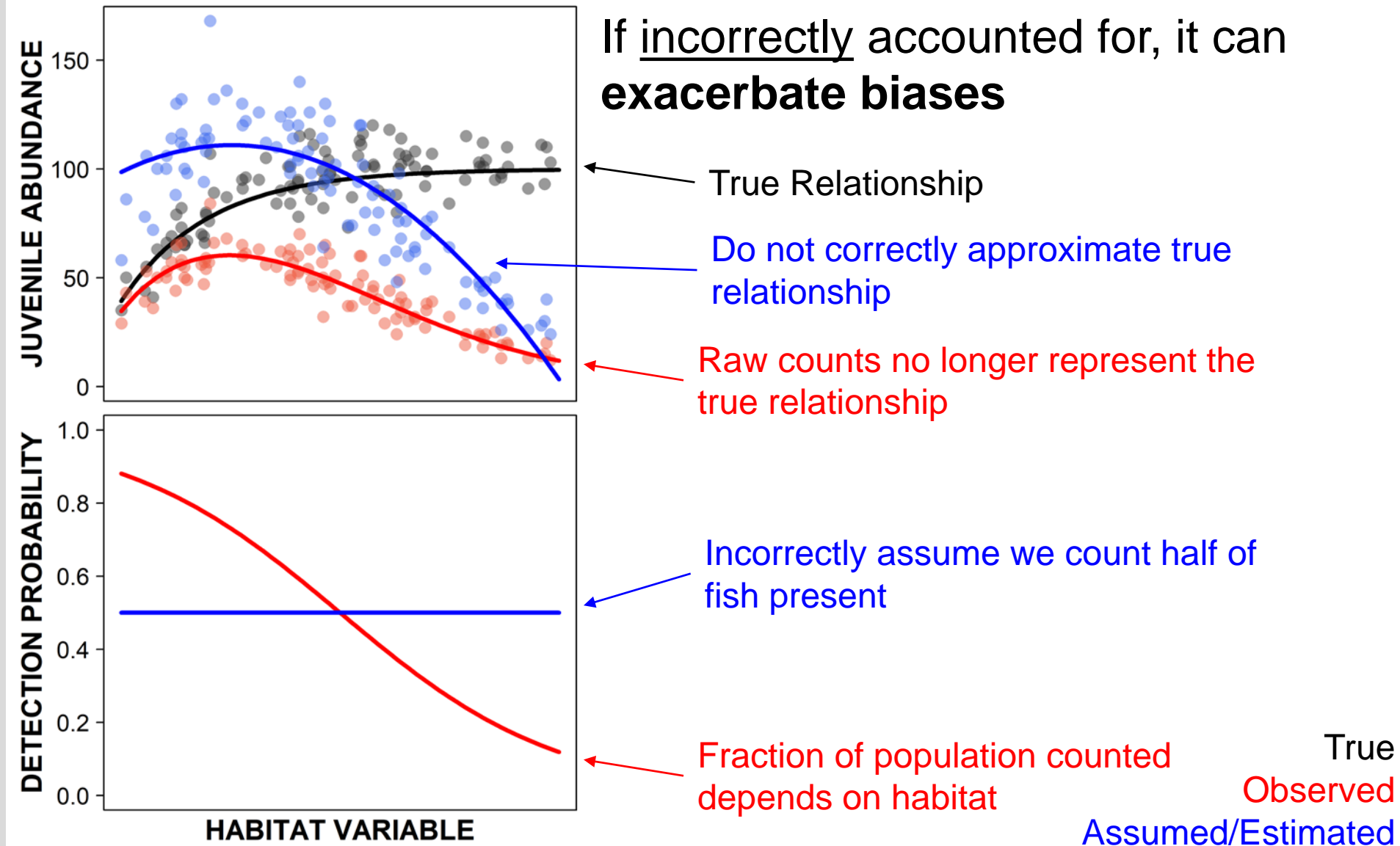
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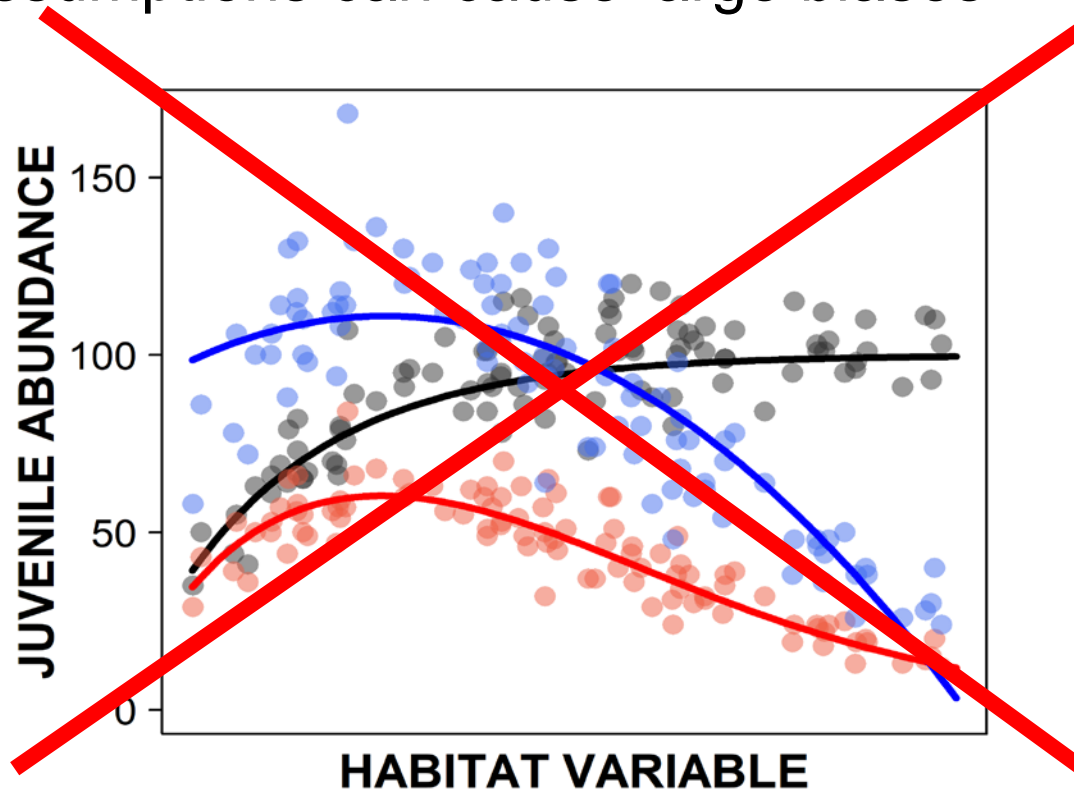
*What can we do about it?*

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# Partial Detectability in Snorkel Surveys

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# Partial Detectability in Snorkel Surveys

*What can we do about it?*

- Make assumptions about factors, direction, and magnitude
  - Bad assumptions can cause large biases
- Conduct **directed studies** to quantify it
  - Must have pairs of snorkel counts and abundance
- How to obtain abundance?
  - Depletion estimators (*keep removing fish until you don't catch any more*)
  - Repeated count estimators (*N-mixture models*)
  - Mark-recapture estimators (*based on fraction of population with marks*)

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*Assumptions difficult to meet, much fish handling, very labor intensive*



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*What can we do about it?*

- Make assumptions about factors, direction, and magnitude
  - Bad assumptions can cause large biases
- Conduct **directed studies** to quantify it
  - Must have pairs of snorkel counts and abundance
  - Count/abundance = efficiency -> link to habitat
- How to obtain abundance?
  - Depletion estimators *Assumptions difficult to meet, much*
  - Repeated count estimators *fish handling, very labor intensive*
  - Mark-recapture estimators *“Middle ground” on these*

# Quantifying Partial Detectability

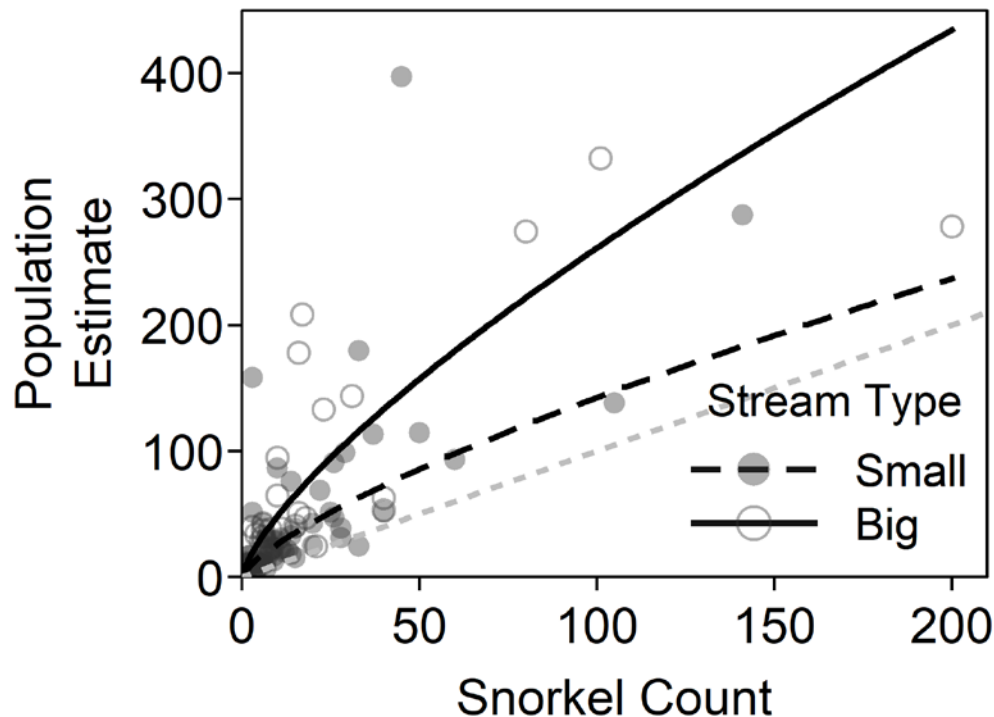
*ODFW/CRITFC study*

- Summers of 2012/2015; Grande Ronde Basin
- At a wide variety of habitat types:
  - (1) Snorkel the channel unit
  - (2) Insert block nets
  - (3) Capture fish and mark them (*electrofishing + fin clips*)
  - (4) Allow population to mix
  - (5) Capture fish and count recaptures + novel captures
  - (6) Remove block nets
- Obtain a statistical relationship for correcting snorkel counts for partial detectability
- ~100 paired snorkel counts and abundance estimates

# Quantifying Partial Detectability

*The current approach*

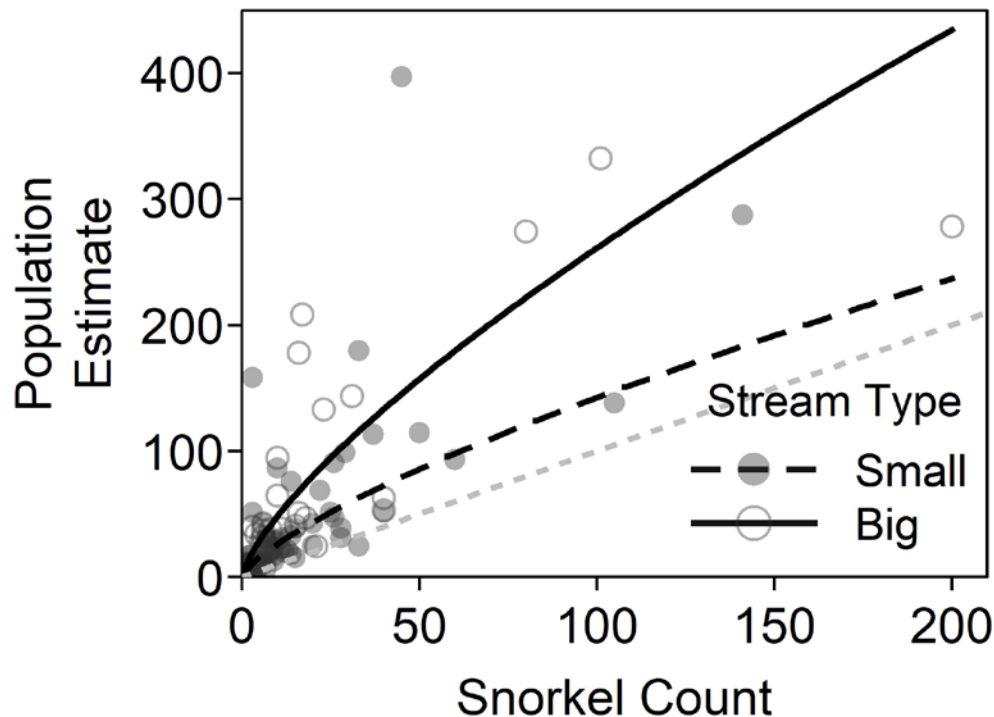
- Regression: predict total salmonid abundance directly from snorkel count
- Same count gives different abundance in small vs. large streams



# Quantifying Partial Detectability

*Potential problems with the current approach*

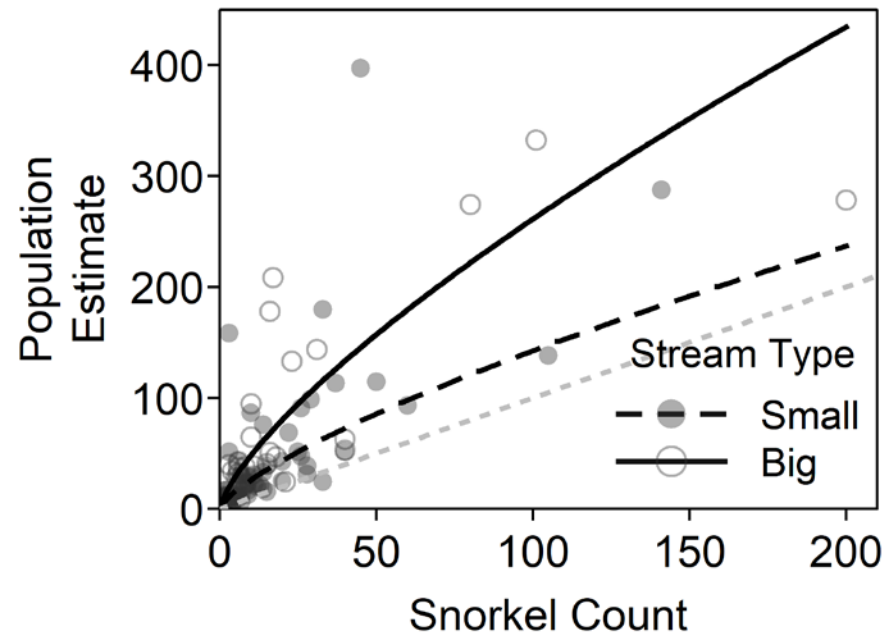
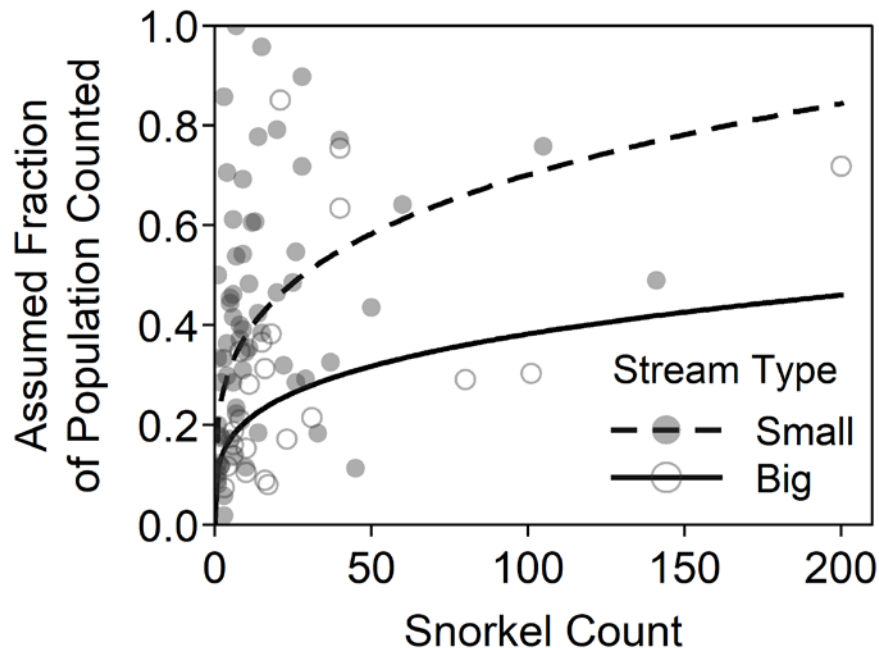
- The population estimate is highly uncertain, ignored
- Assumes stream size (binary) is the only factor impacting detection
- Assumes all salmonids are equally detectable



# Quantifying Partial Detectability

## *Potential problems with the current approach*

- The population estimate is highly uncertain, ignored
- Assumes stream size (binary) is the only factor impacting detection
- Assumes all salmonids are equally detectable
- Assumes detection probability is a function of count





# Rethinking Partial Detectability

*As a binomial process*

- $N$  fish in channel unit  $j$ 
  - Outcome 1: individual  $i$  is seen (with probability  $p_j$ )
  - Outcome 2: individual  $i$  is not seen (with probability  $1 - p_j$ )
- $p_j$  is a complex function of
  - Habitat conditions, fish behavior, snorkeler aptitude
- If  $N$  is known, we can estimate  $p$  as a function of these covariates via logistic regression

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- **If  $N$  is known**, we can estimate  $p$  as a function of these covariates via logistic regression

## **PROBLEM**

$N$  is not known! Mark-recapture provides an estimate of  $N$ , with substantial uncertainty due to sampling variability

## **SOLUTION**

Treat  $N$  as a latent parameter and apply a joint likelihood to explain both mark-recapture and snorkel data

# Estimation of Partial Detectability

*Layout of hierarchical model*

**Standard 2-Sample  
Mark-Recapture  
Estimator**

**Logistic Regression**

**KEY**

Parameter

Observable Quantity

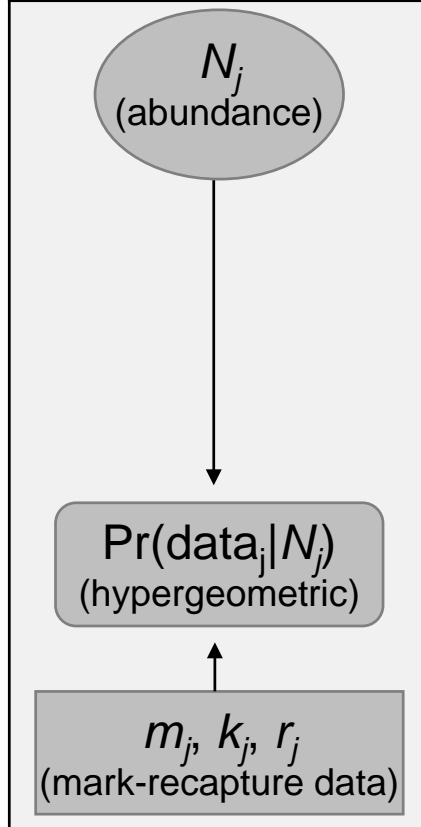
Derived Quantity

Likelihood Function

# Estimation of Partial Detectability

*Layout of hierarchical model*

## Standard 2-Sample Mark-Recapture Estimator



## Logistic Regression

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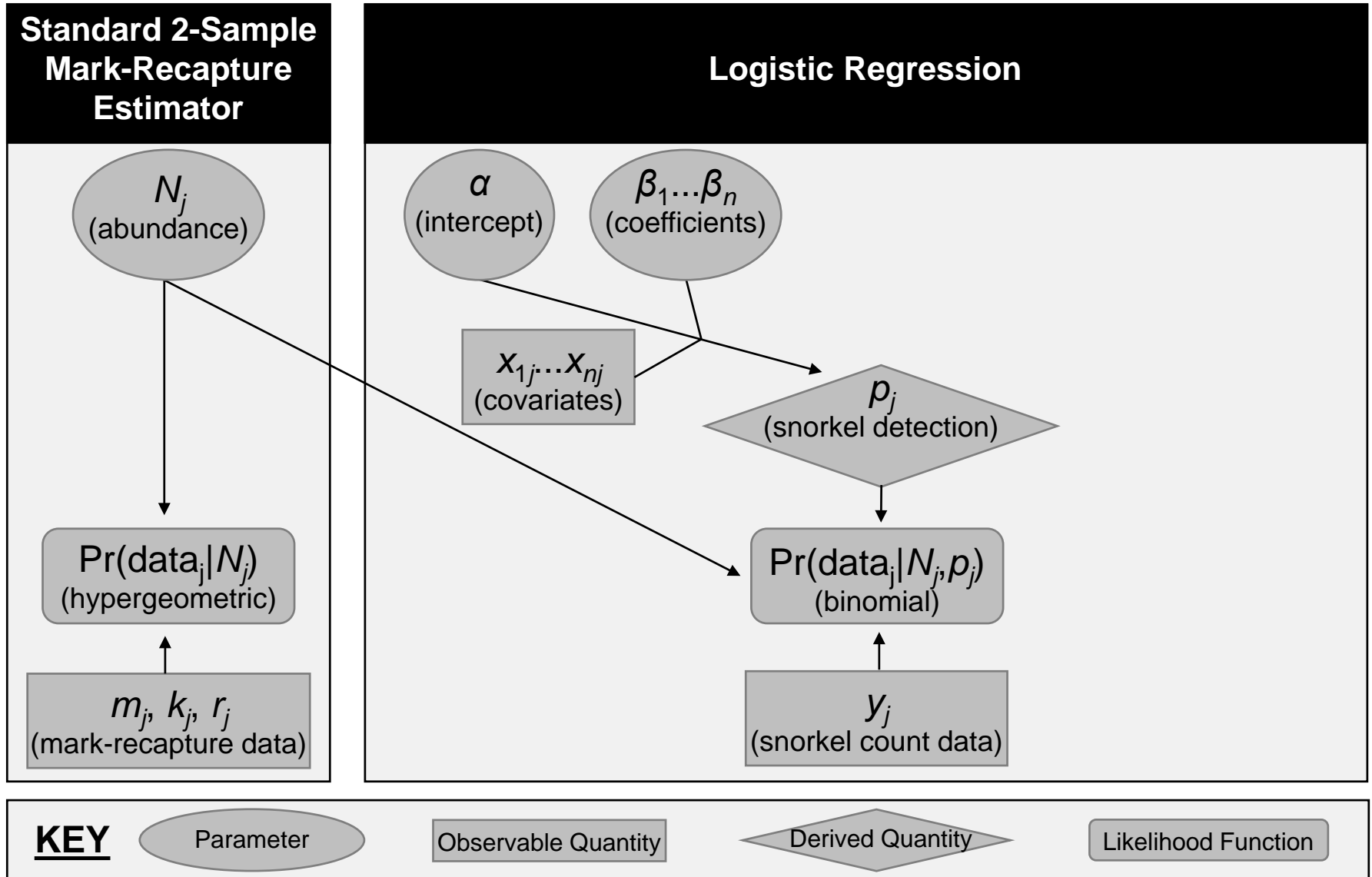
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# Estimation of Partial Detectability

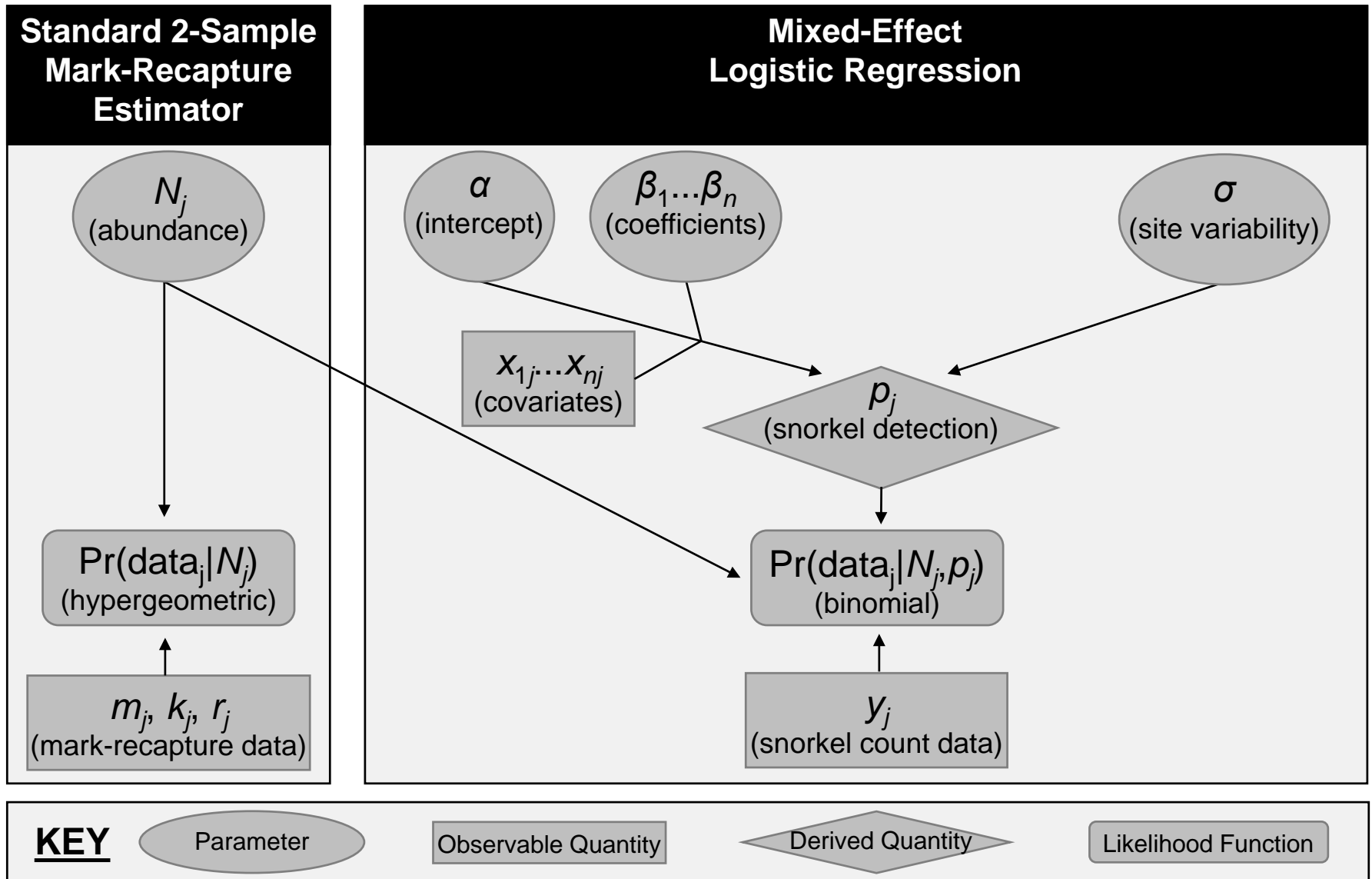
## *Layout of hierarchical model*





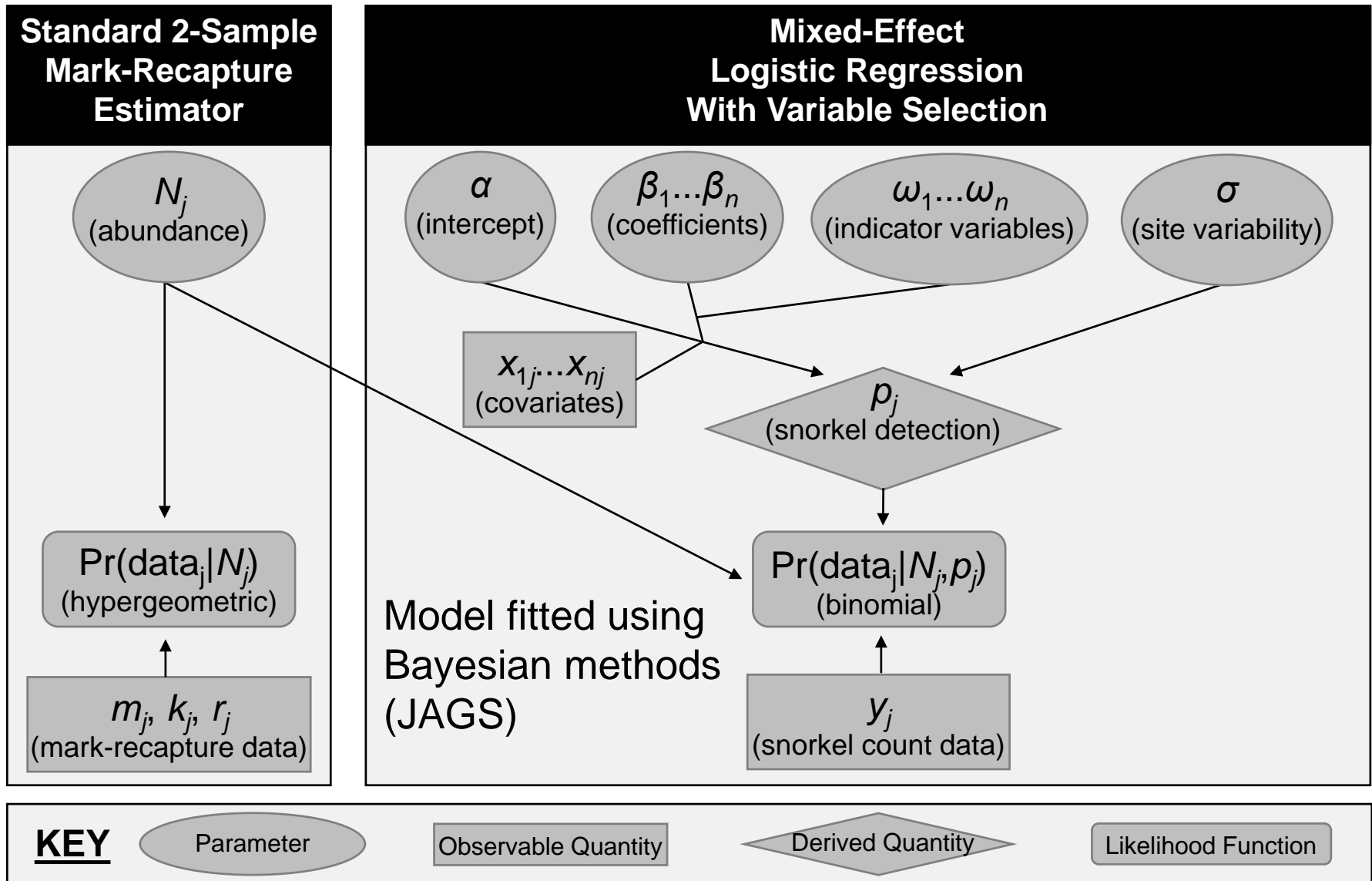
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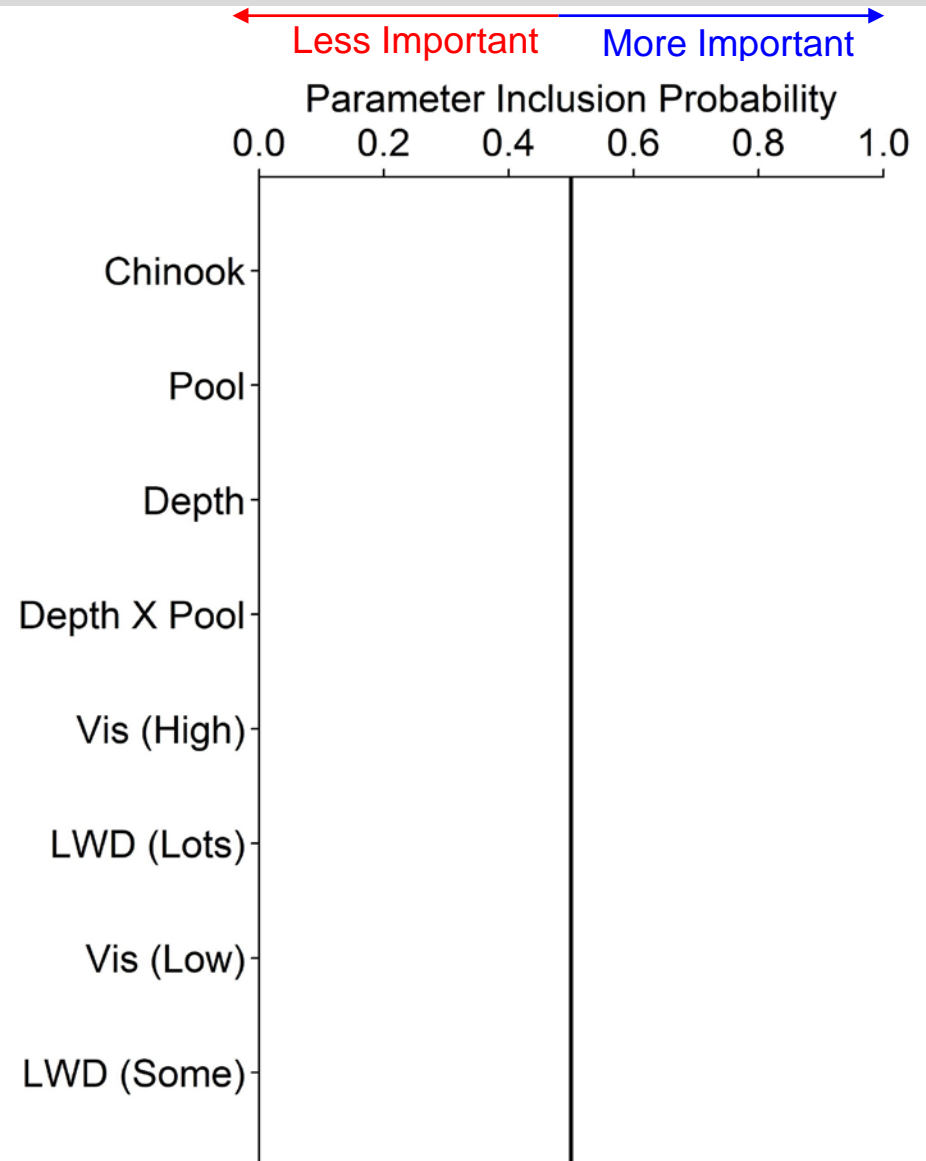
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# Results

*Variable importance: parameter inclusion probability*

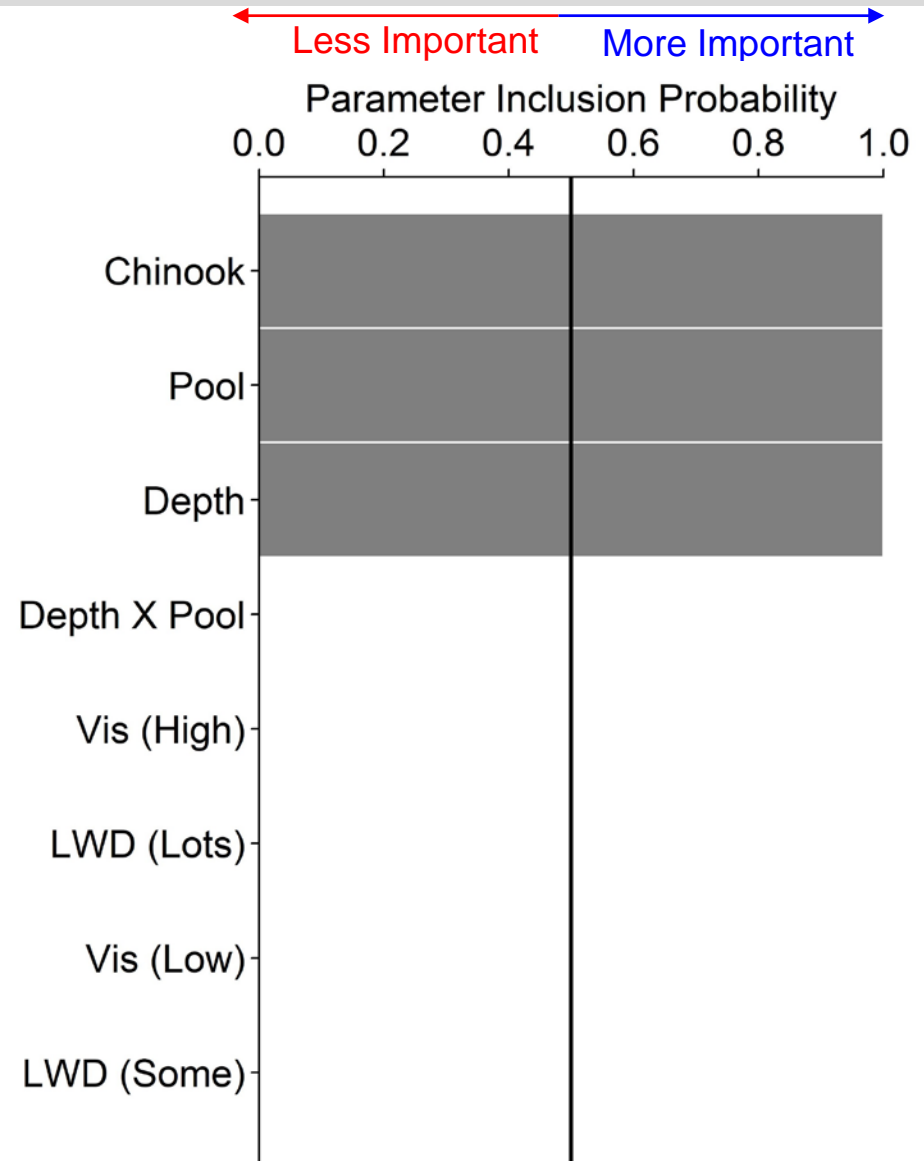


# Results

*Variable importance: parameter inclusion probability*

- Strong evidence for  $p$  varying with

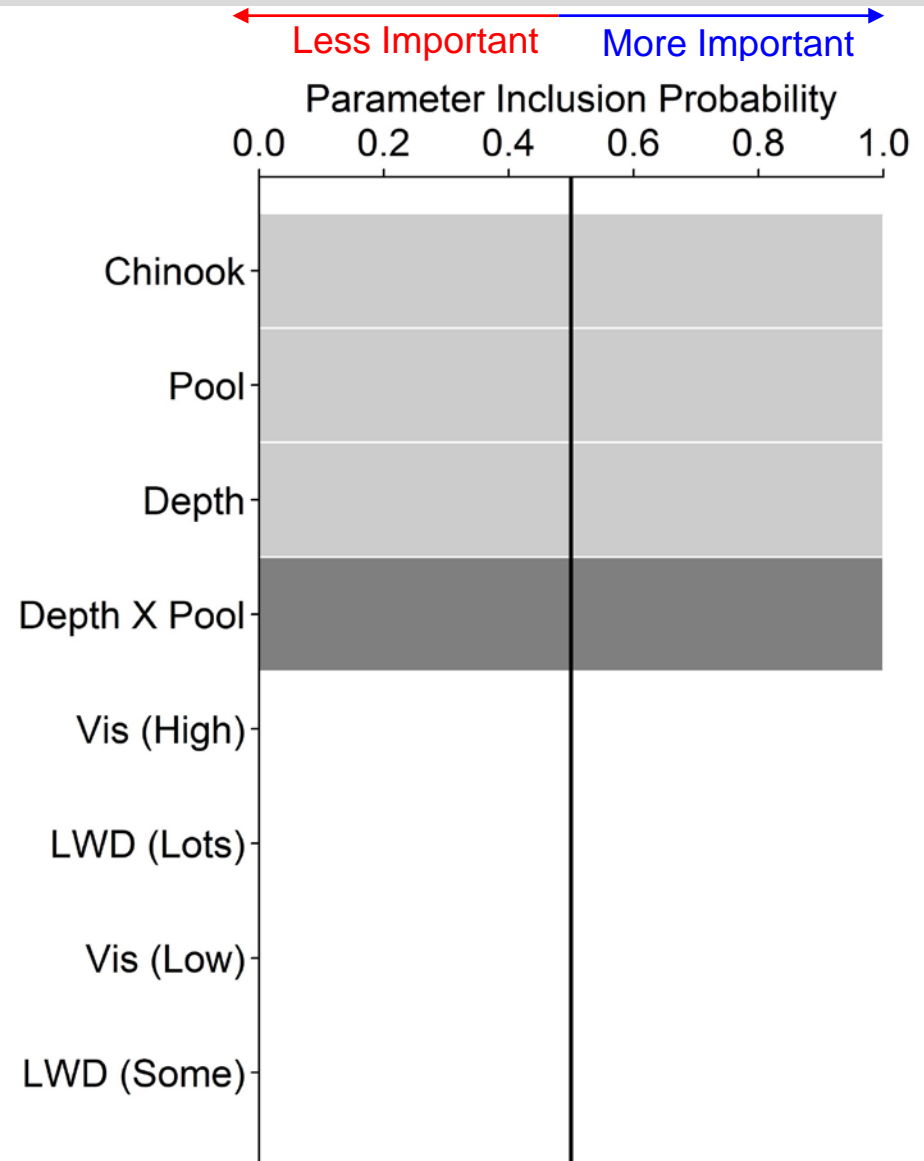
- Species
- Unit type
- Depth



# Results

*Variable importance: parameter inclusion probability*

- Strong evidence for  $p$  varying with
  - Species
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- Effect of depth depends on unit type

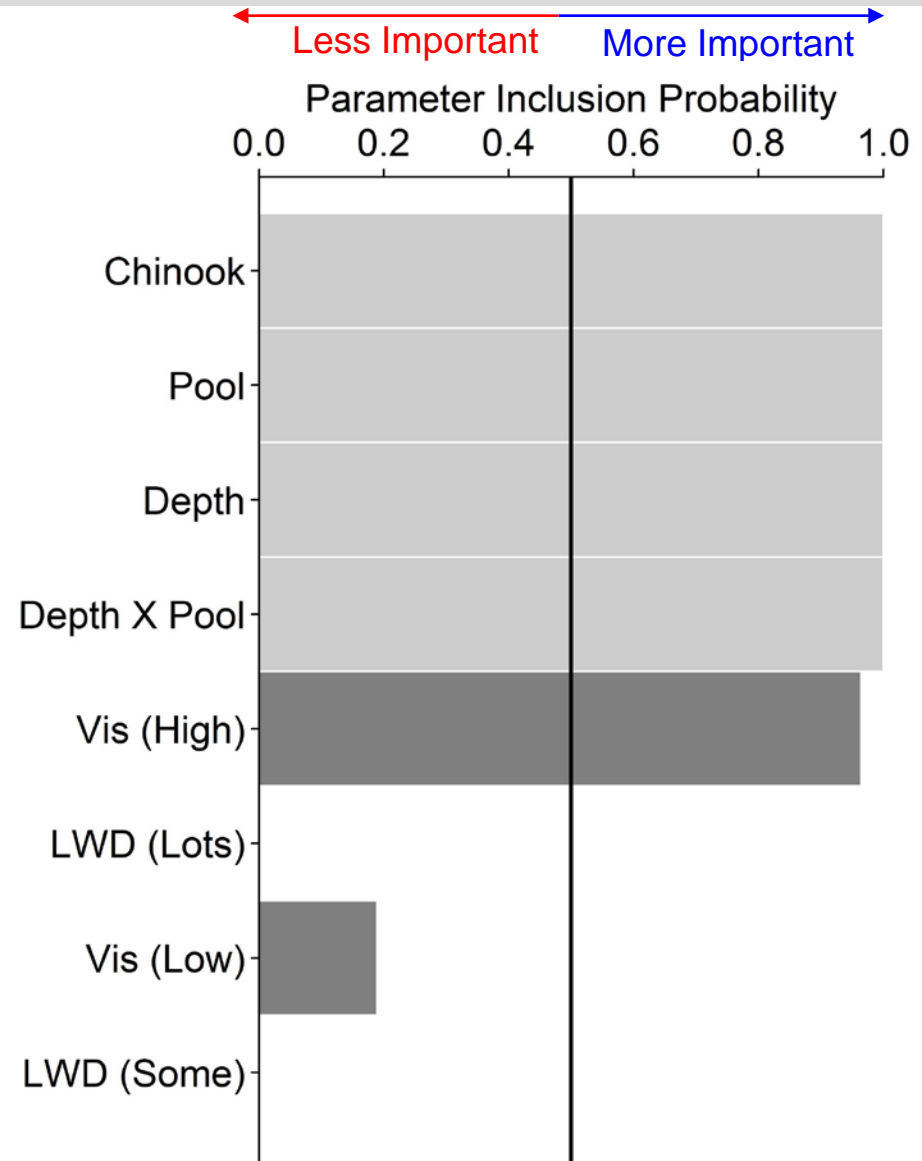




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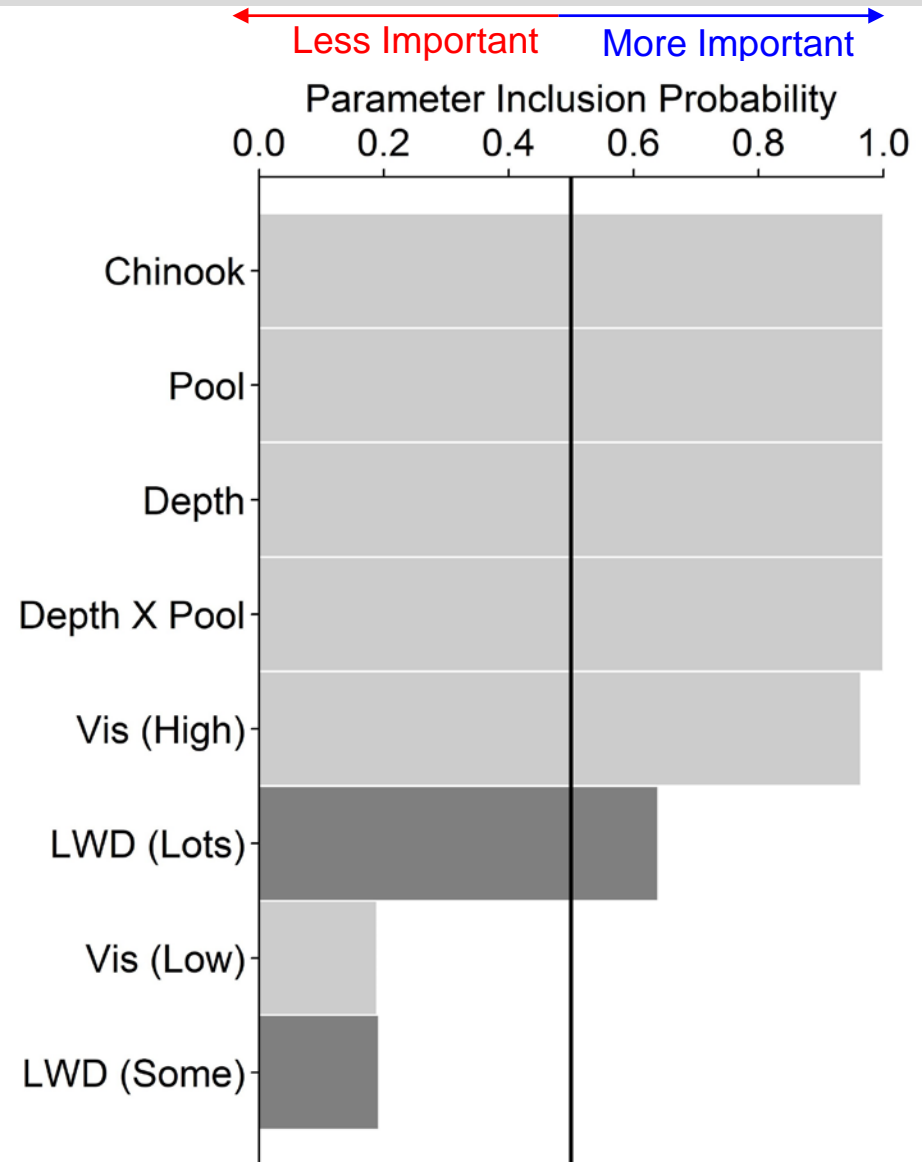
- Strong evidence for  $p$  varying with
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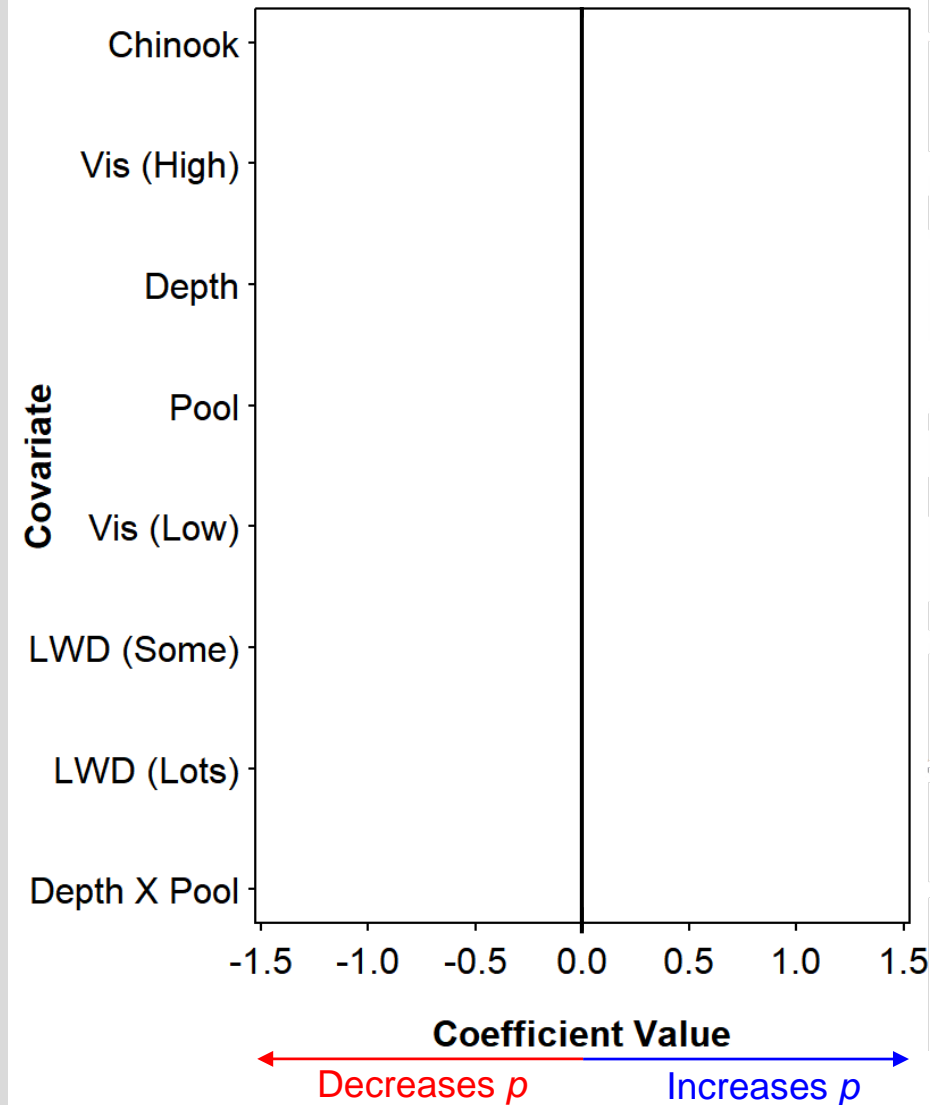
- Strong evidence for  $p$  varying with
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- Wood only important if there is lots of it



# Results

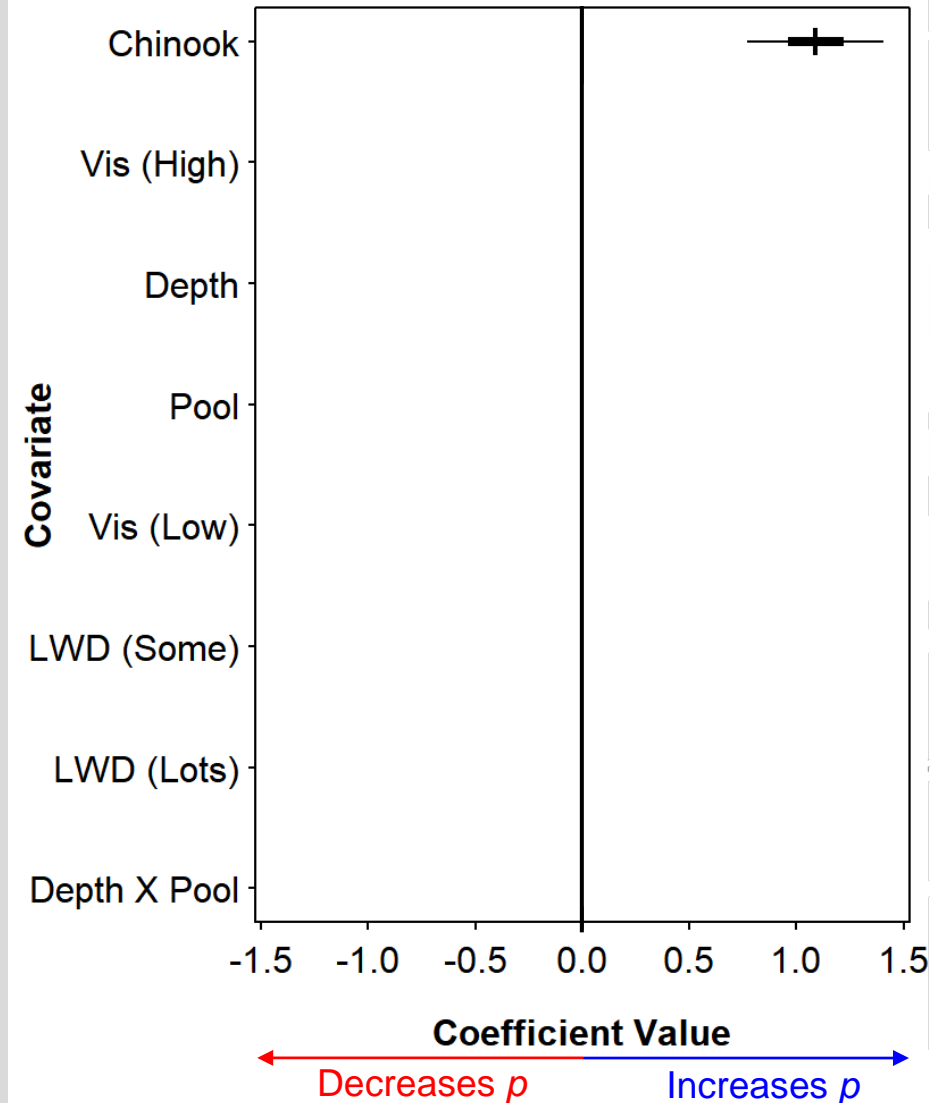
*Effect sizes and direction: model-averaged*

- Intuitive effect directions



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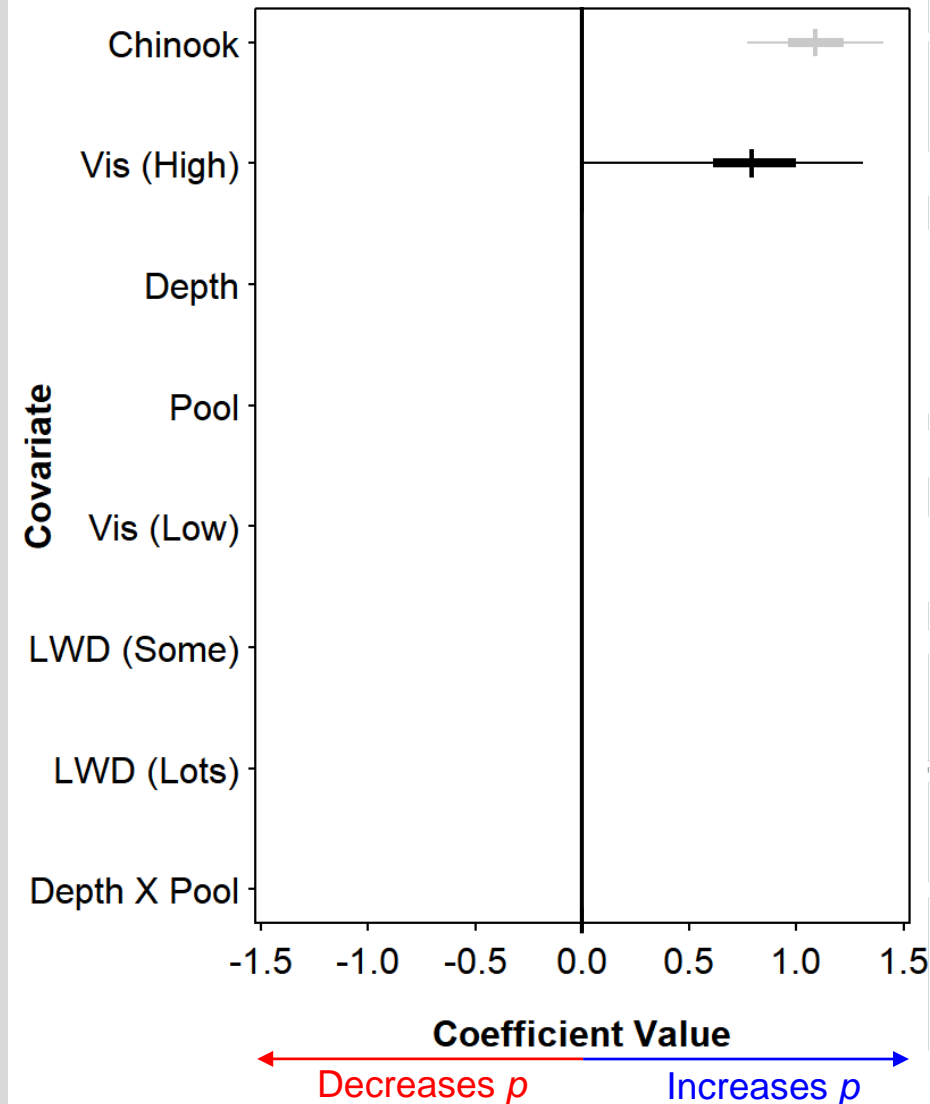
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- Intuitive effect directions
  - Chinook easier to see than steelhead

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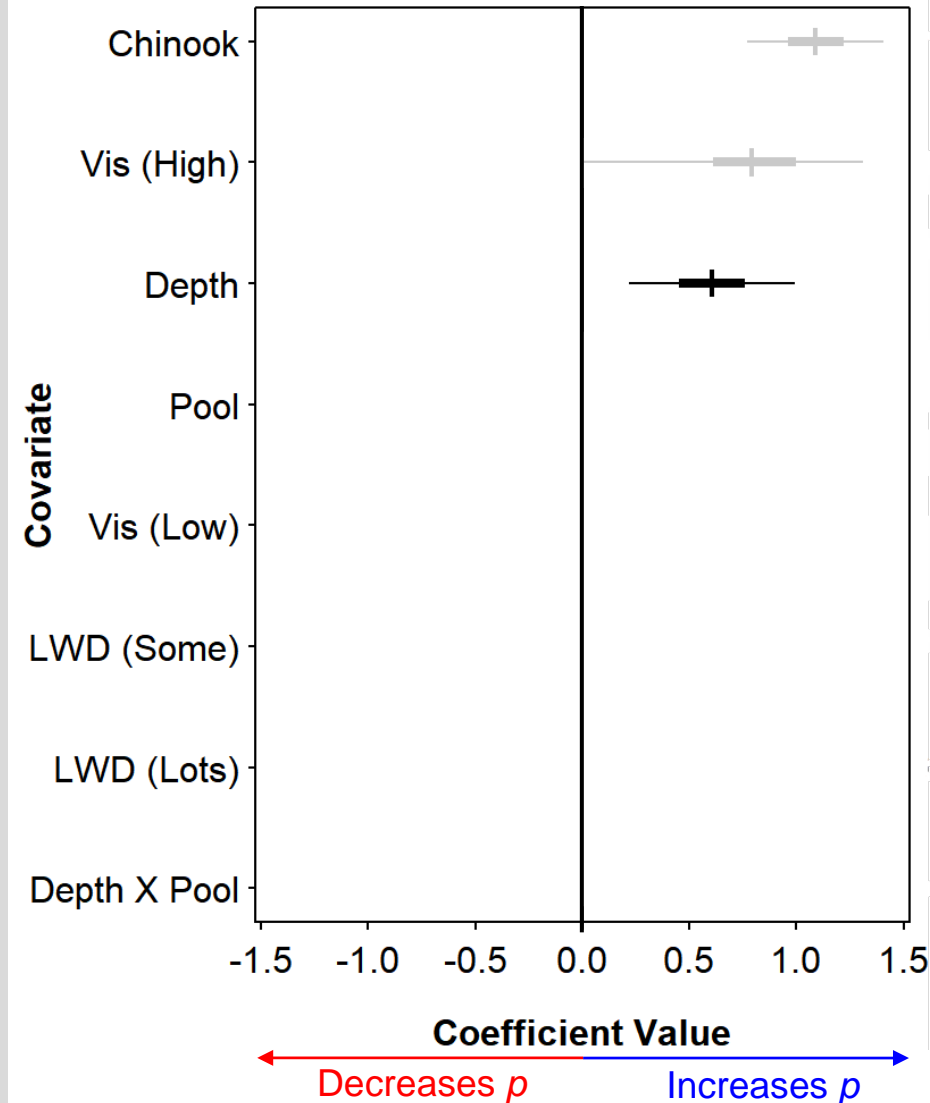


- Intuitive effect directions

- Chinook easier to see than steelhead
- High visibility increases detection

# Results

*Effect sizes and direction: model-averaged*



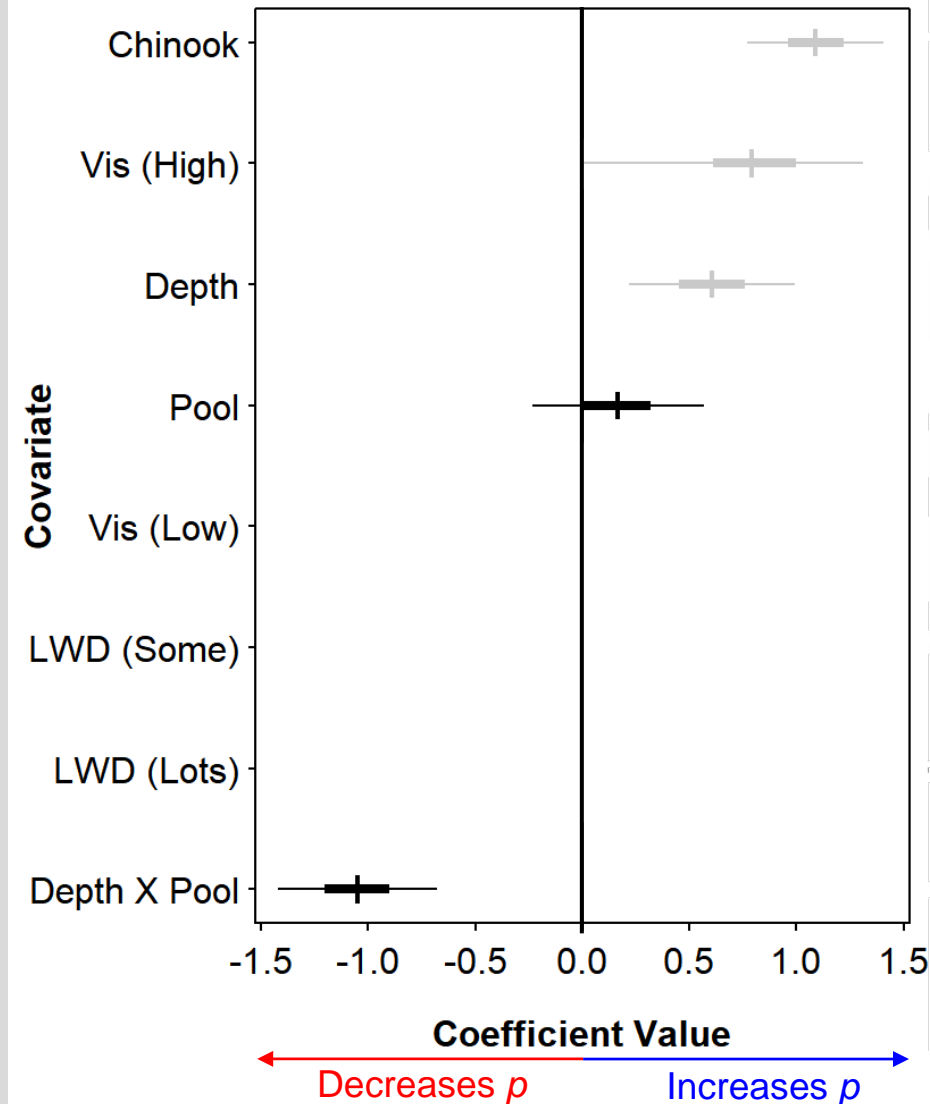
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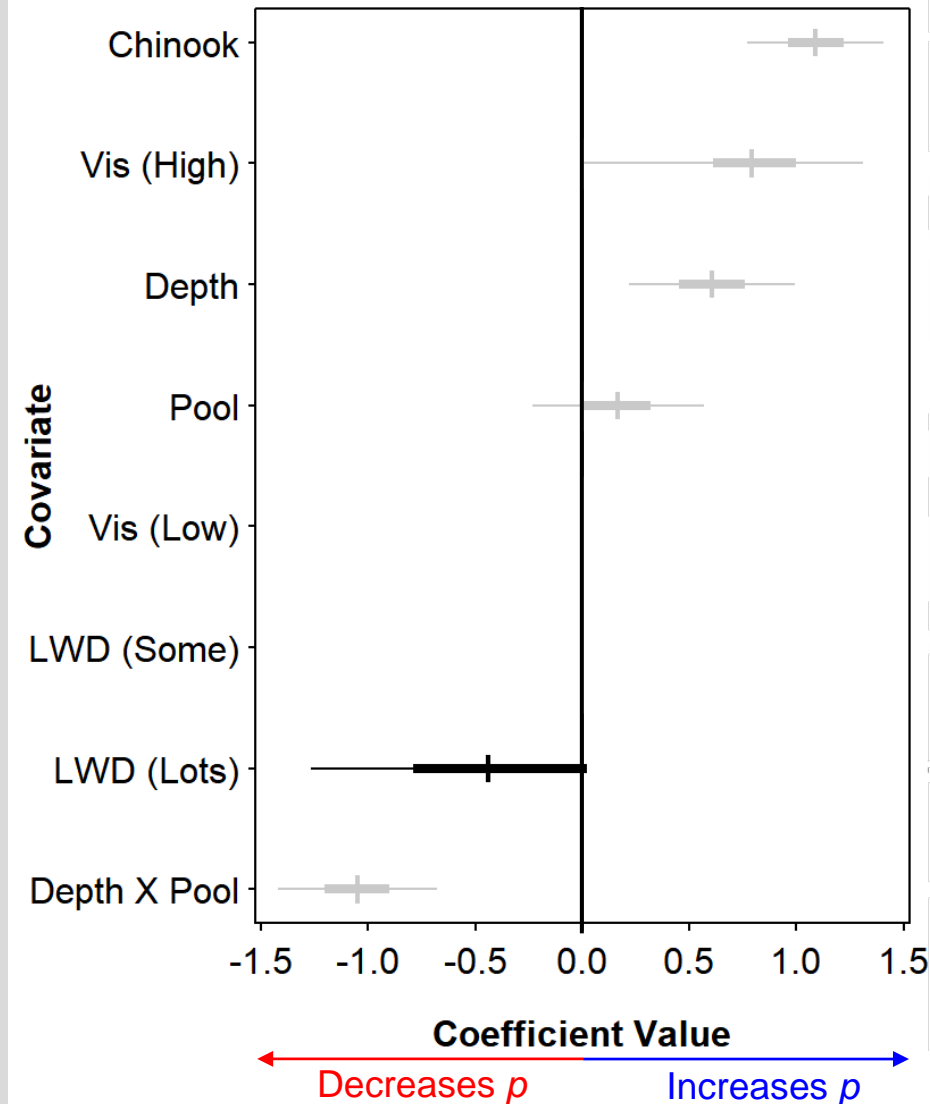


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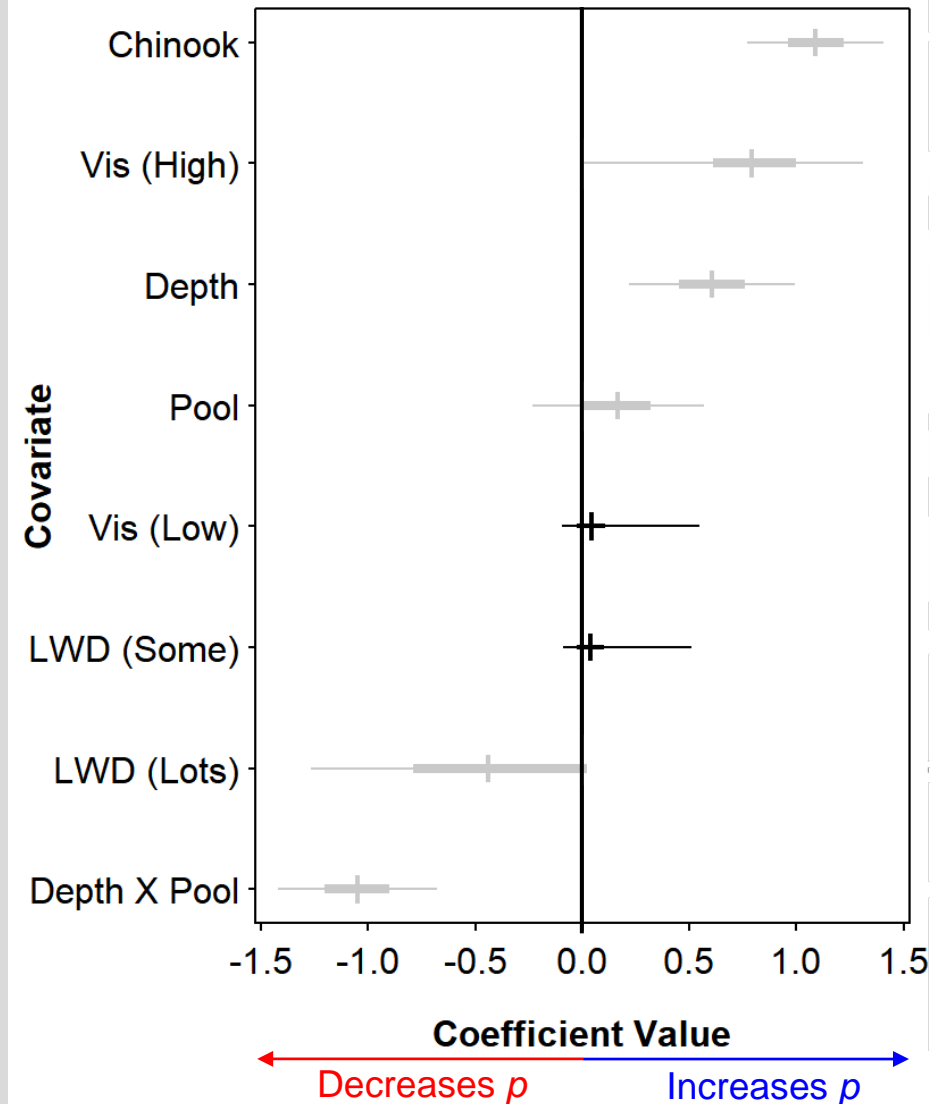


- Intuitive effect directions

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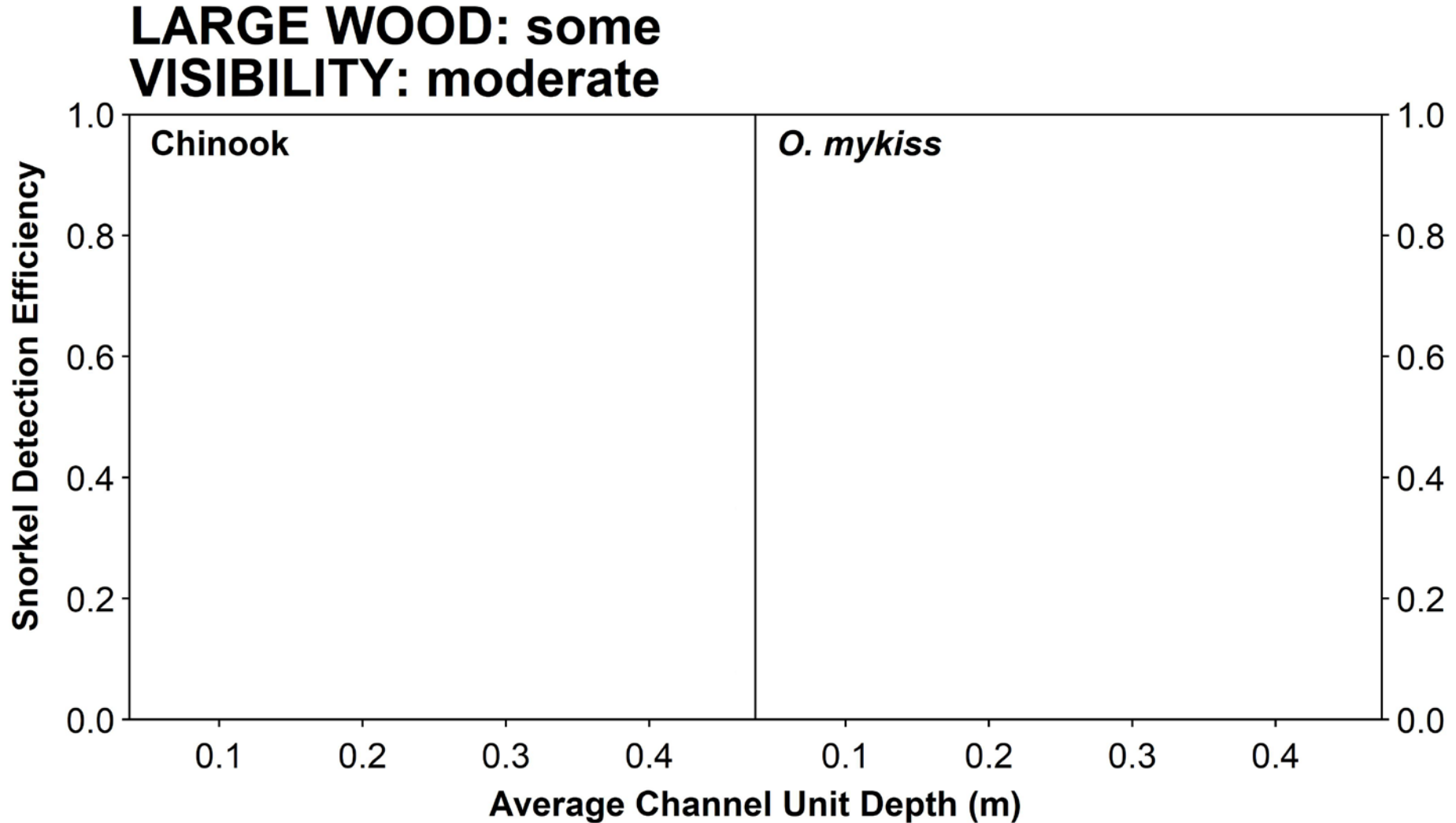


- **Intuitive effect directions**

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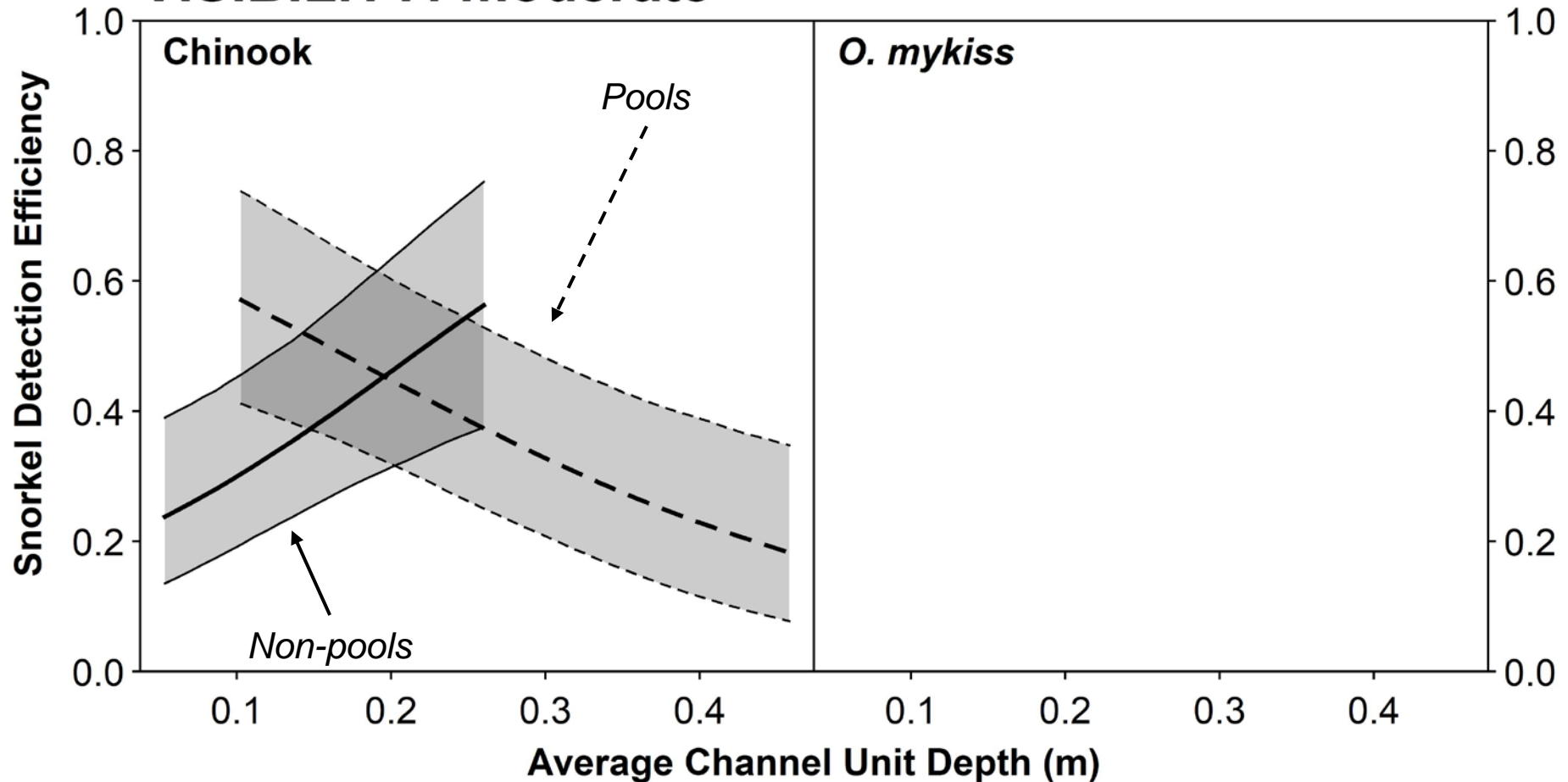
Effect sizes and direction: typical conditions



# Results

Effect sizes and direction: **typical** conditions

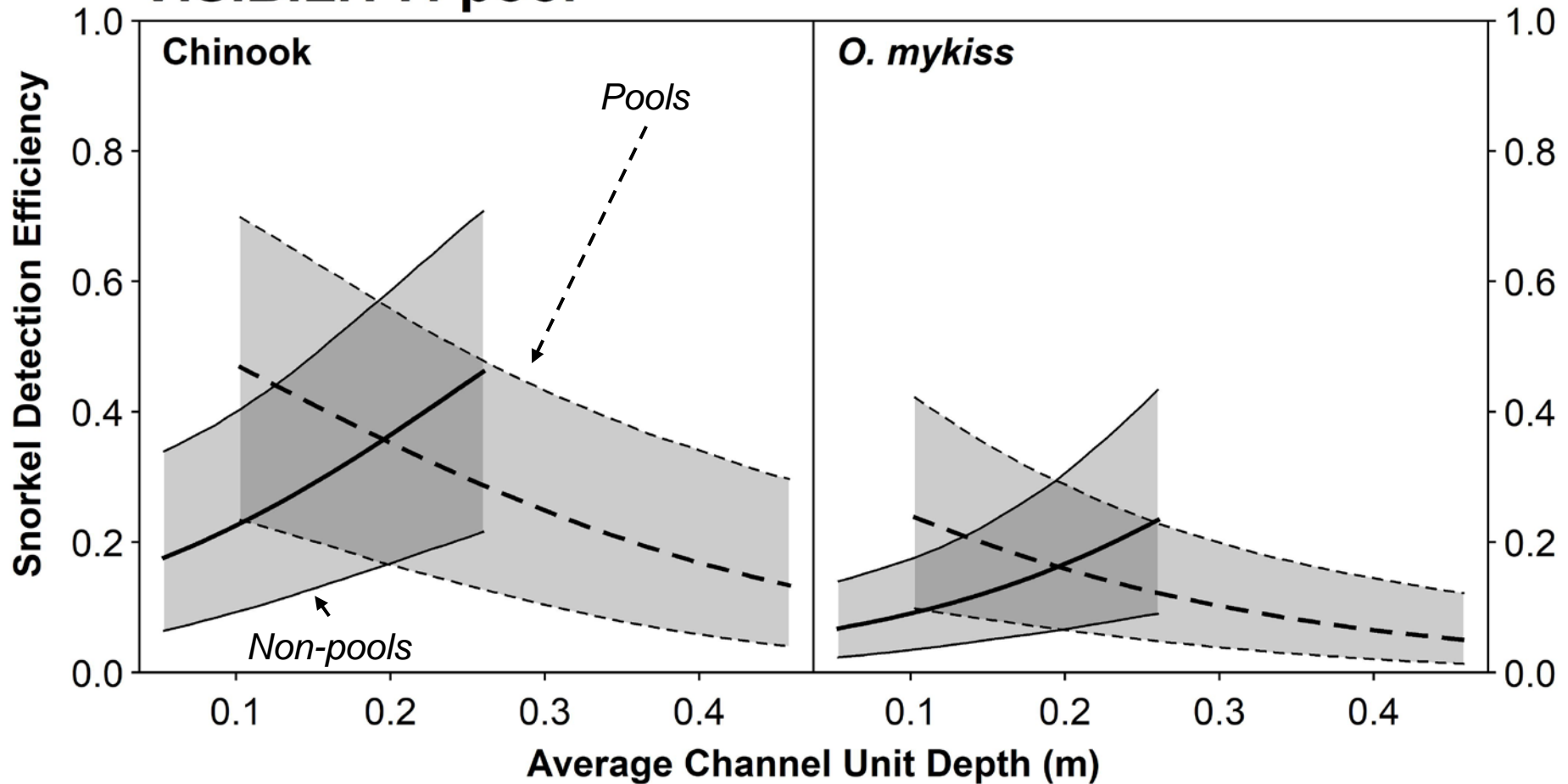
**LARGE WOOD: some**  
**VISIBILITY: moderate**



# Results

Effect sizes and direction: **poor** snorkel conditions

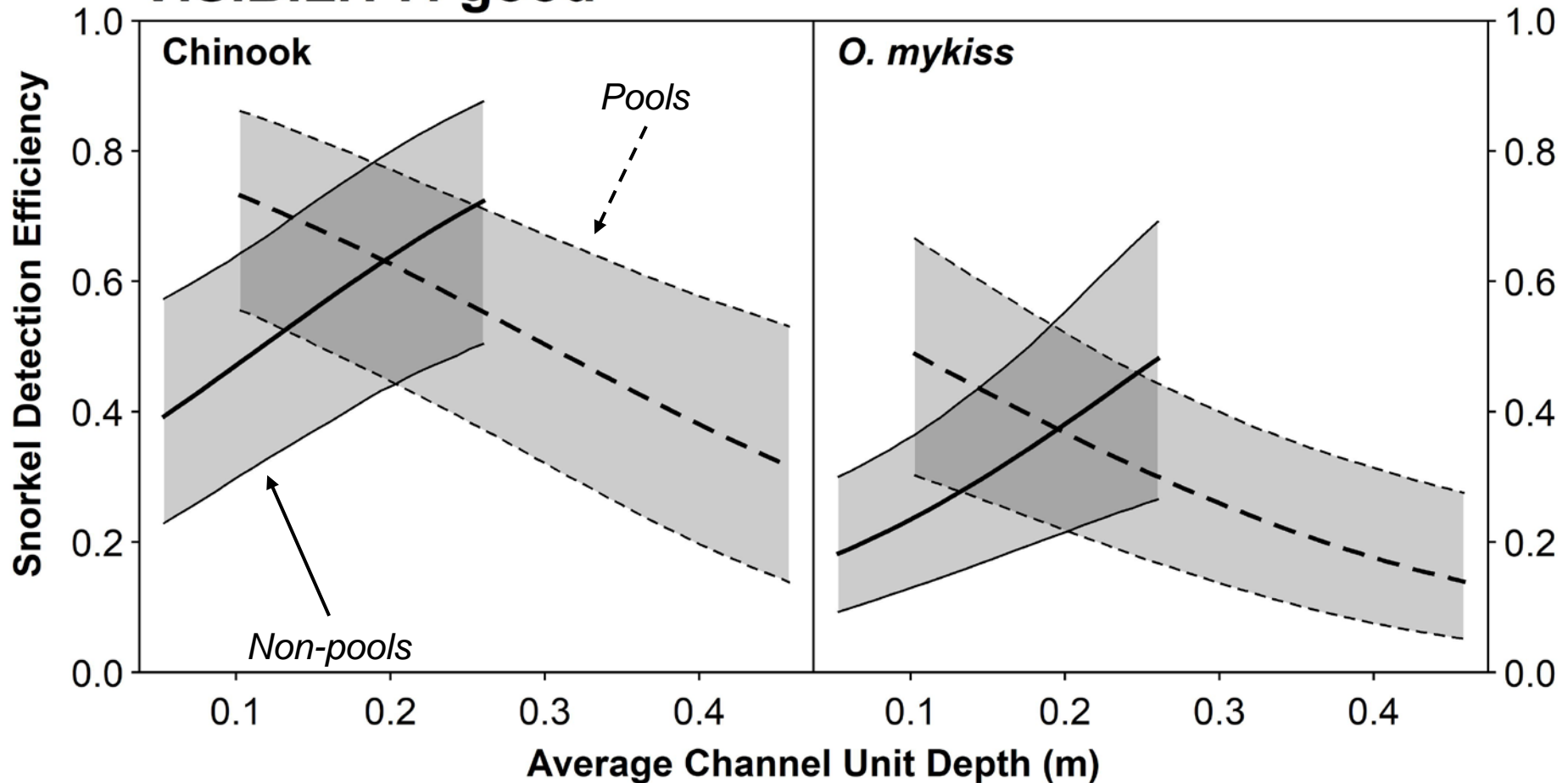
**LARGE WOOD: lots  
VISIBILITY: poor**



# Results

Effect sizes and direction: good snorkel conditions

**LARGE WOOD: none**  
**VISIBILITY: good**





# Summary

## *Strengths and Weaknesses*

### **WEAKNESSES**

- Lots of random site variability
- Observer-specific effects?  
Year effects?
- Inference limited to channel units with similar characteristics
- Is count process truly binomial? (*independent, homogenous  $p$* )

### **STRENGTHS**

- Direct estimates of detection probability
- How it changes with local conditions
- Acknowledges uncertainty in mark-recapture sampling
- Output is automatically model-averaged (usage of  $\omega_i$  terms)

### **NEXT STEPS: SIMULATION TRIALS**

- Sensitive to violated assumptions?
- Necessary sample size?
- Incredibly uninformative mark-recapture data?

# Questions?

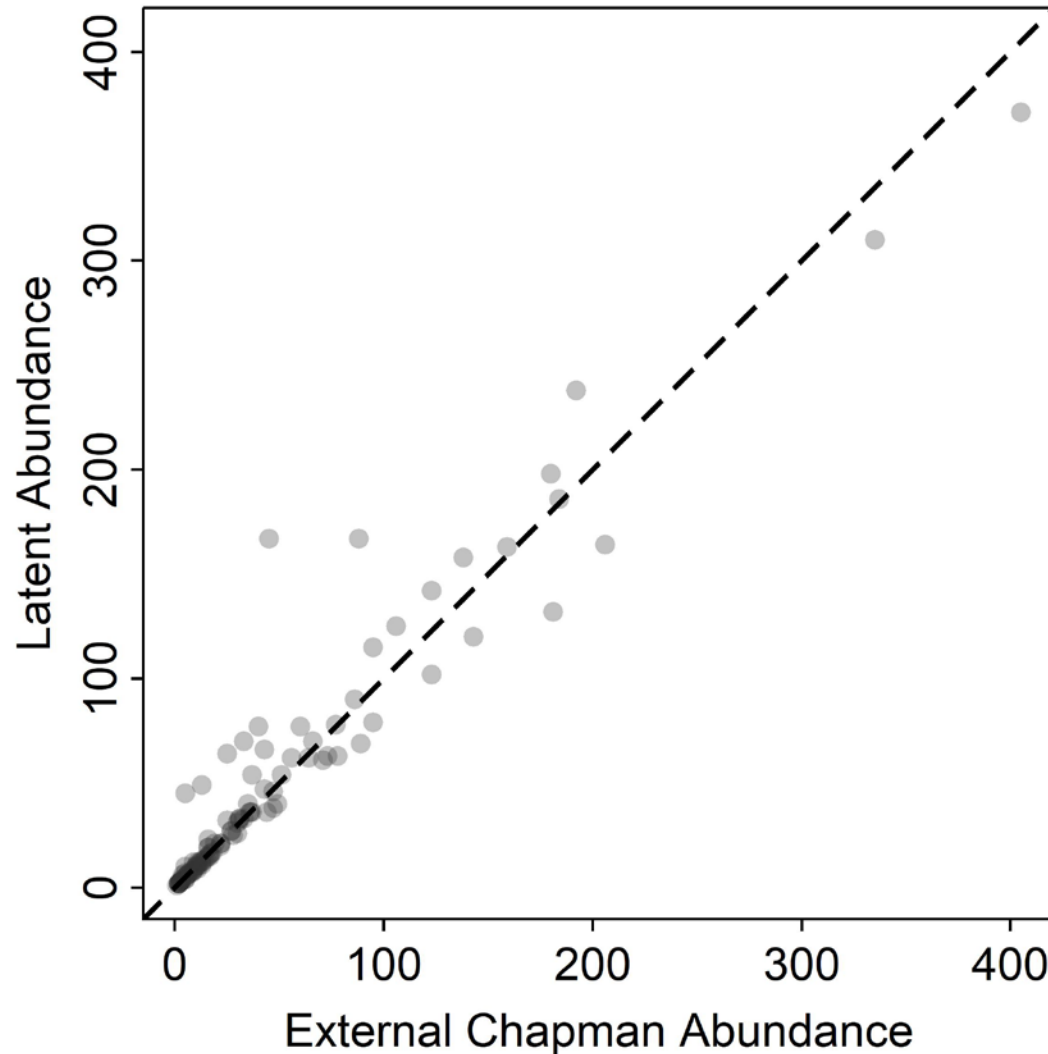


Ben Staton  
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**BONUS  
SLIDES**

# Abundance Estimates

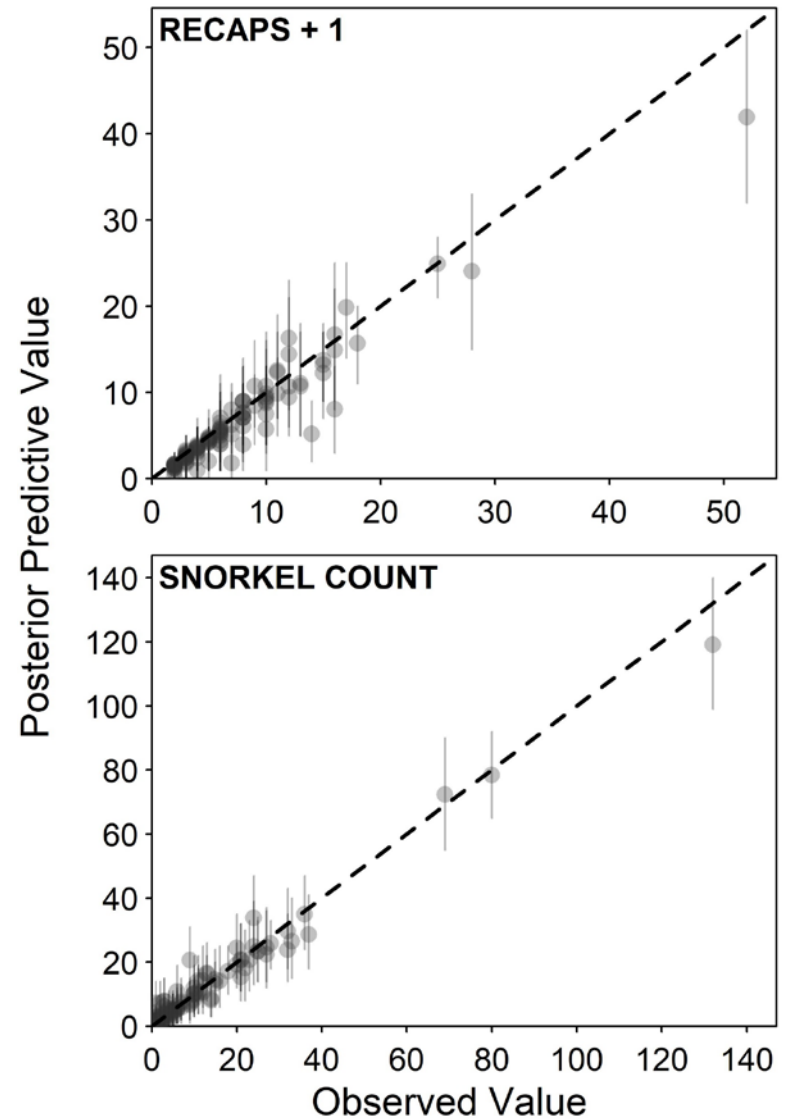
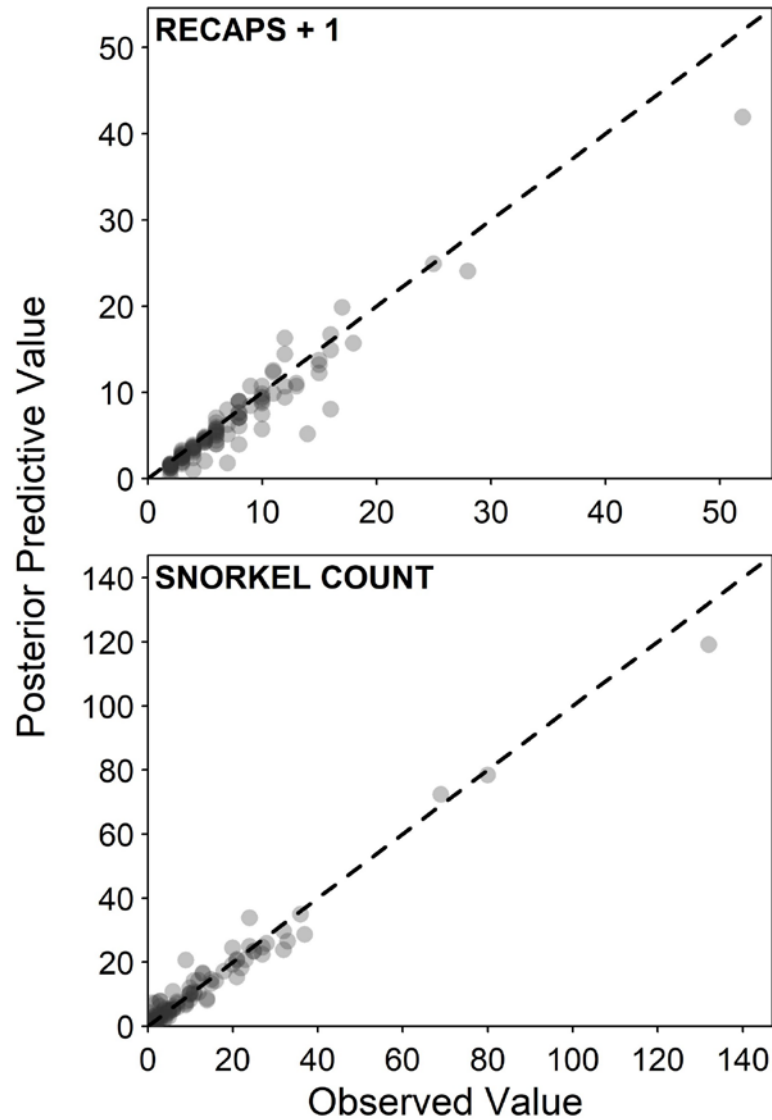
*Hierarchical vs. external Chapman estimates*



Hierarchical (latent) abundance estimate does not always equal the Chapman estimate

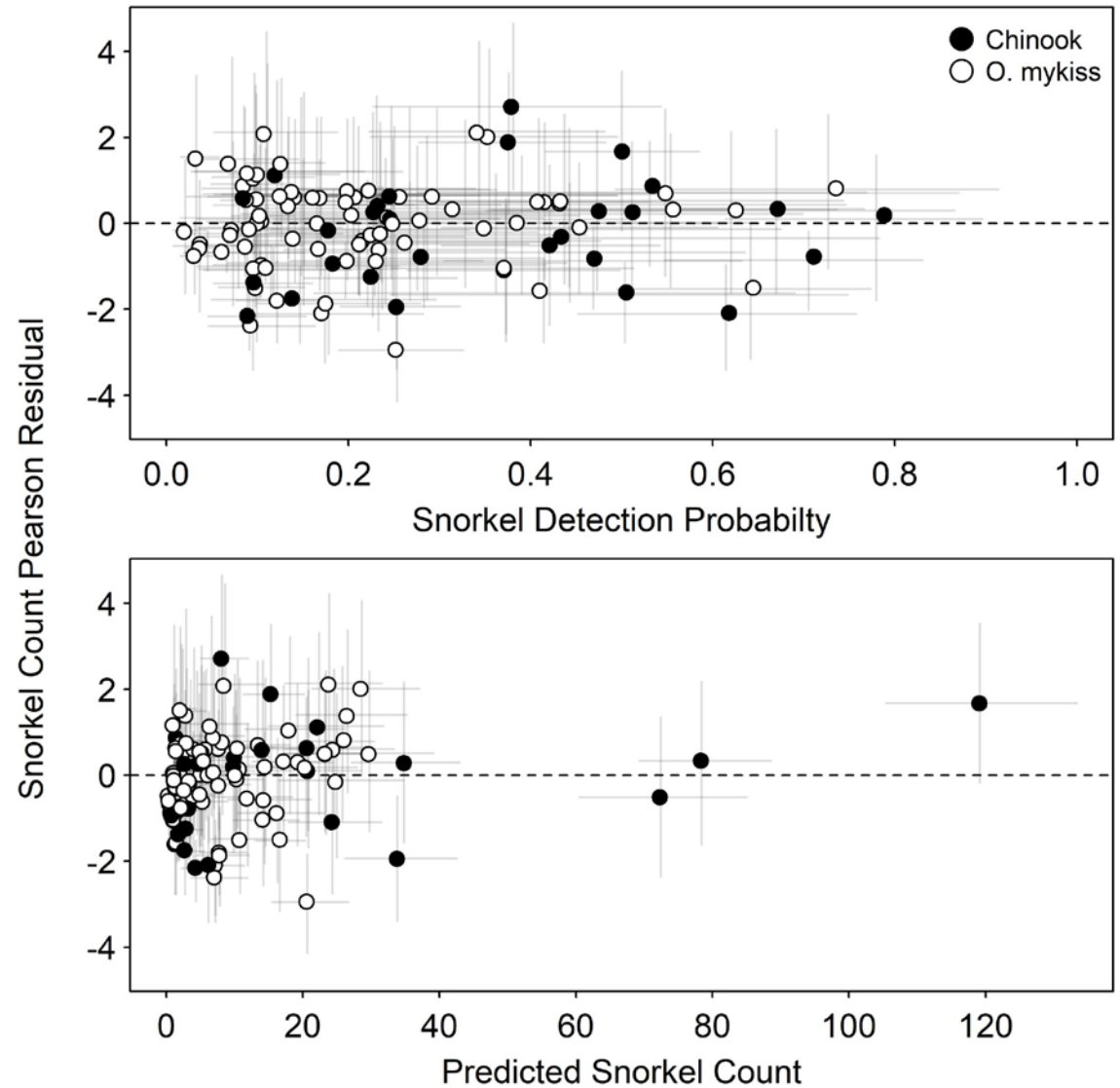
Model must satisfy **both** snorkel and mark-recap data

# Fit to Data



# Residual Inspection

No residual patterns  
in snorkel data



# Pseudo JAGS Code

```
model {  
  # PRIORS: ABUNDANCE  
  for (i in 1:nobs) {  
    Nu[i] ~ dunif(minN[i], maxN)  
    N[i] <- round(Nu[i])  
  }  
  
  # PRIORS: LOGIT MODEL COEFFICIENTS  
  a ~ dnorm(0, 0.001)  
  b ~ dnorm(0, 0.001)  
  w ~ dbern(0.5)  
  
  # LIKELIHOOD  
  for (i in 1:nobs) {  
    # mark-recap data  
    recaps1[i] ~ dhyper(marked[i]+1, N[i]-marked[i], K[i]+1, 1)  
  
    # snorkel data  
    snorkel[i] ~ dbin(p[i], N[i])  
    logit(p[i]) <- a + b * w * cvt[i]  
  }  
}
```